

# Tensor-based blind source separation in Magnetic Resonance Spectroscopic Imaging

Bharath Halandur Nagaraja

bhalandu@esat.kuleuven.be

Prof. Sabine Van Huffel

sabine.vanhuffel@kuleuven.be

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# Contents Overview



## 1. Introduction

- Magnetic Resonance Spectroscopic imaging



## 2. Residual Water Suppression

- Hankel-tensor based water suppression
- Löwner-tensor based water suppression



## 3. Tumor tissue type differentiation

- From MRSI
- From MP-MRI



## 4. MRSI tumor voxel classification



## 5. Tumor segmentation from MP-MRI

# | Cancer Diagnostics

UZ Leuven departments

Imaging & Pathology

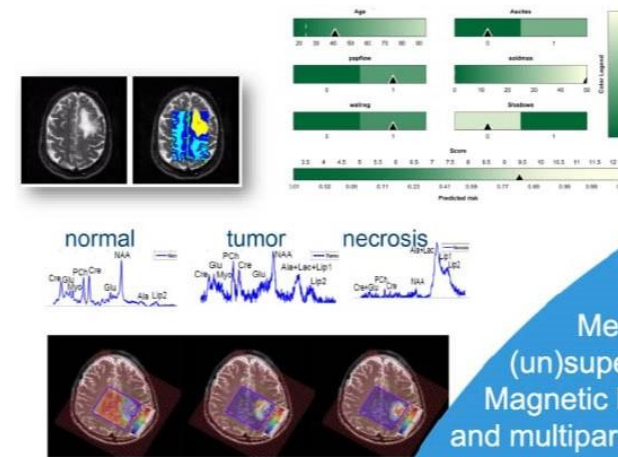
Radiology

Neurosurgery

Development and Regeneration

UZ Gent department

Radiology



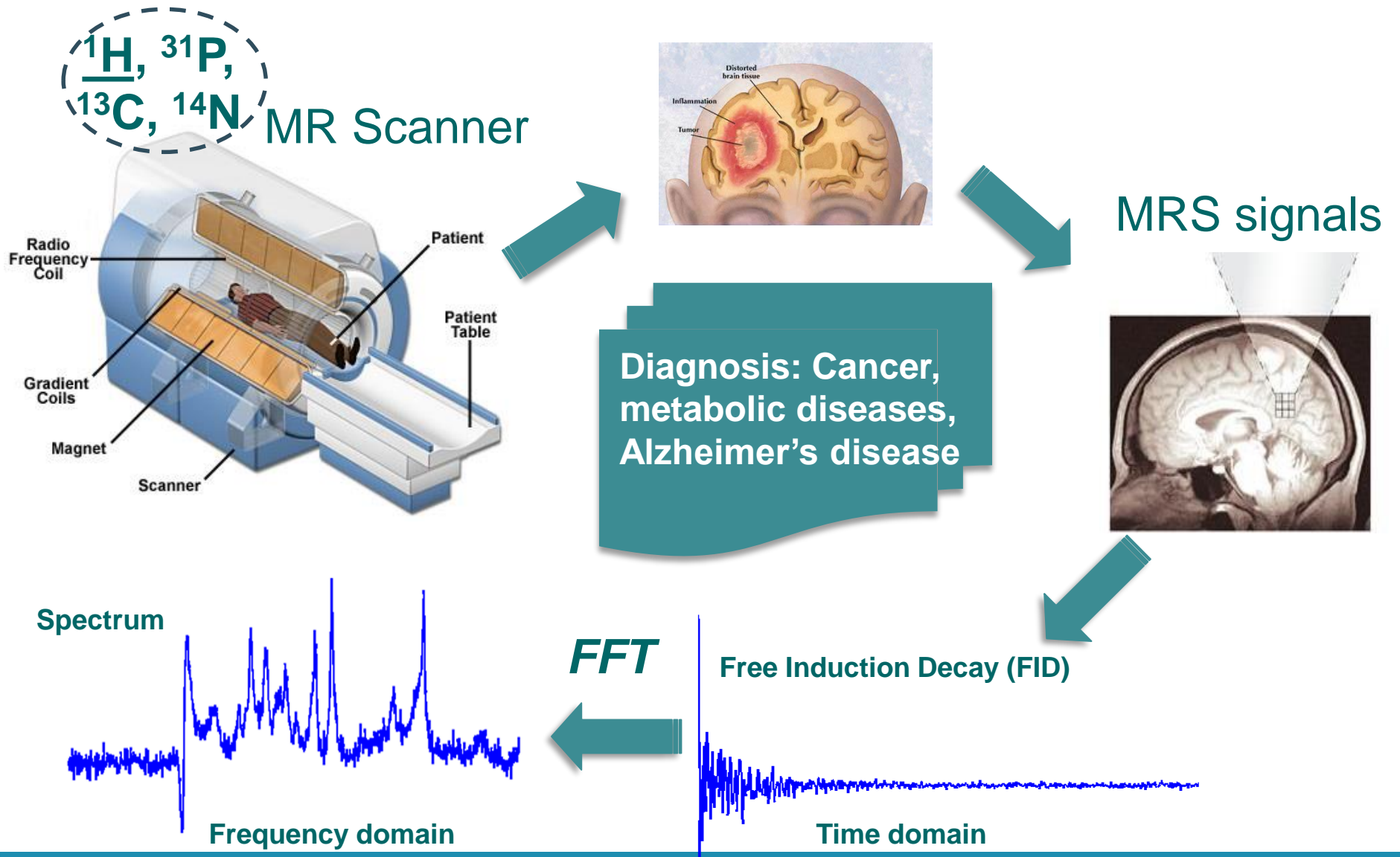
06.

## Cancer Diagnostics

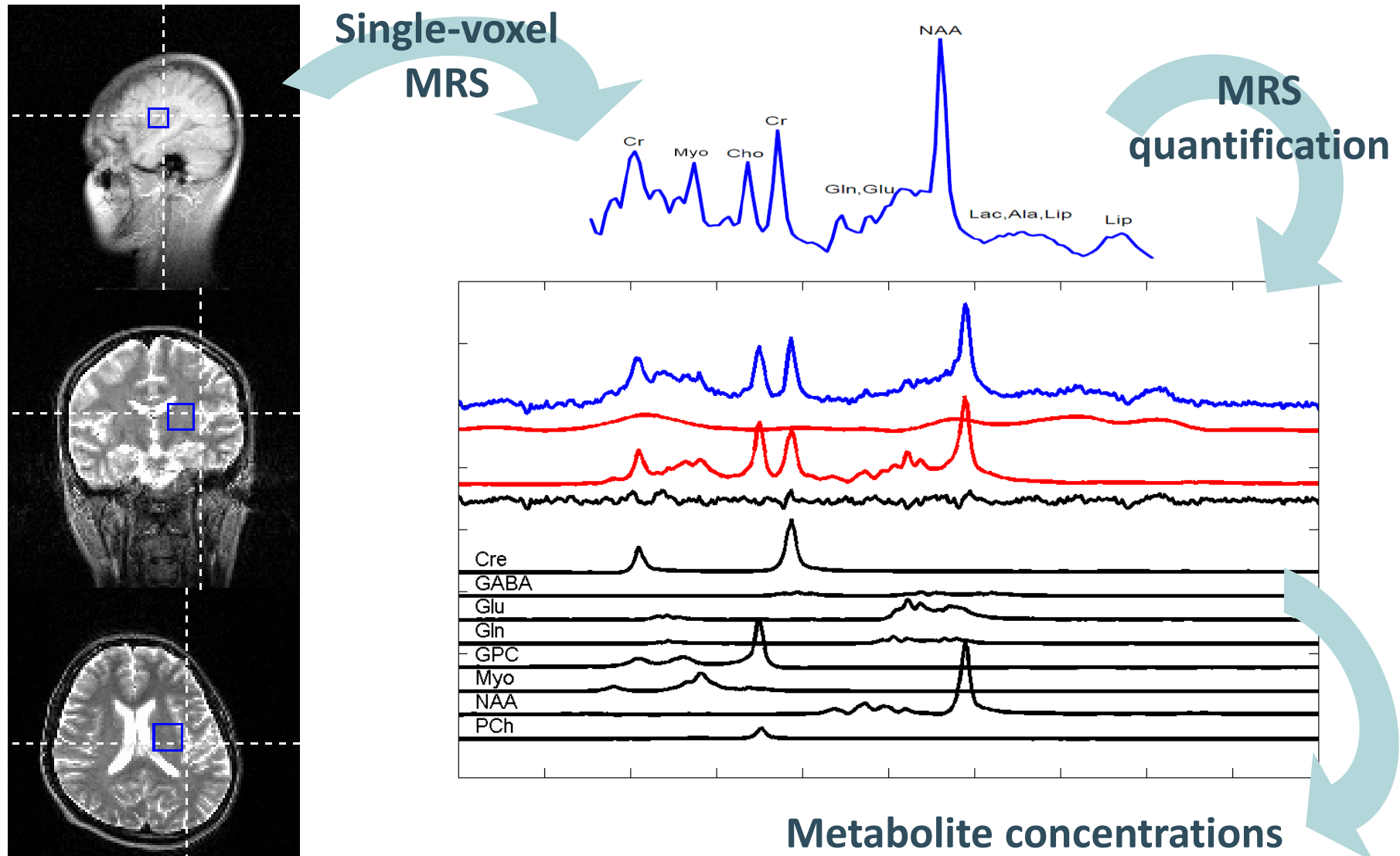
Metabolite quantification and (un)supervised tumor tissue typing using Magnetic Resonance Spectroscopic Imaging and multiparametric MR data fusion, Interpretable Prediction models for preoperative cancer diagnosis.

EXAMPLE

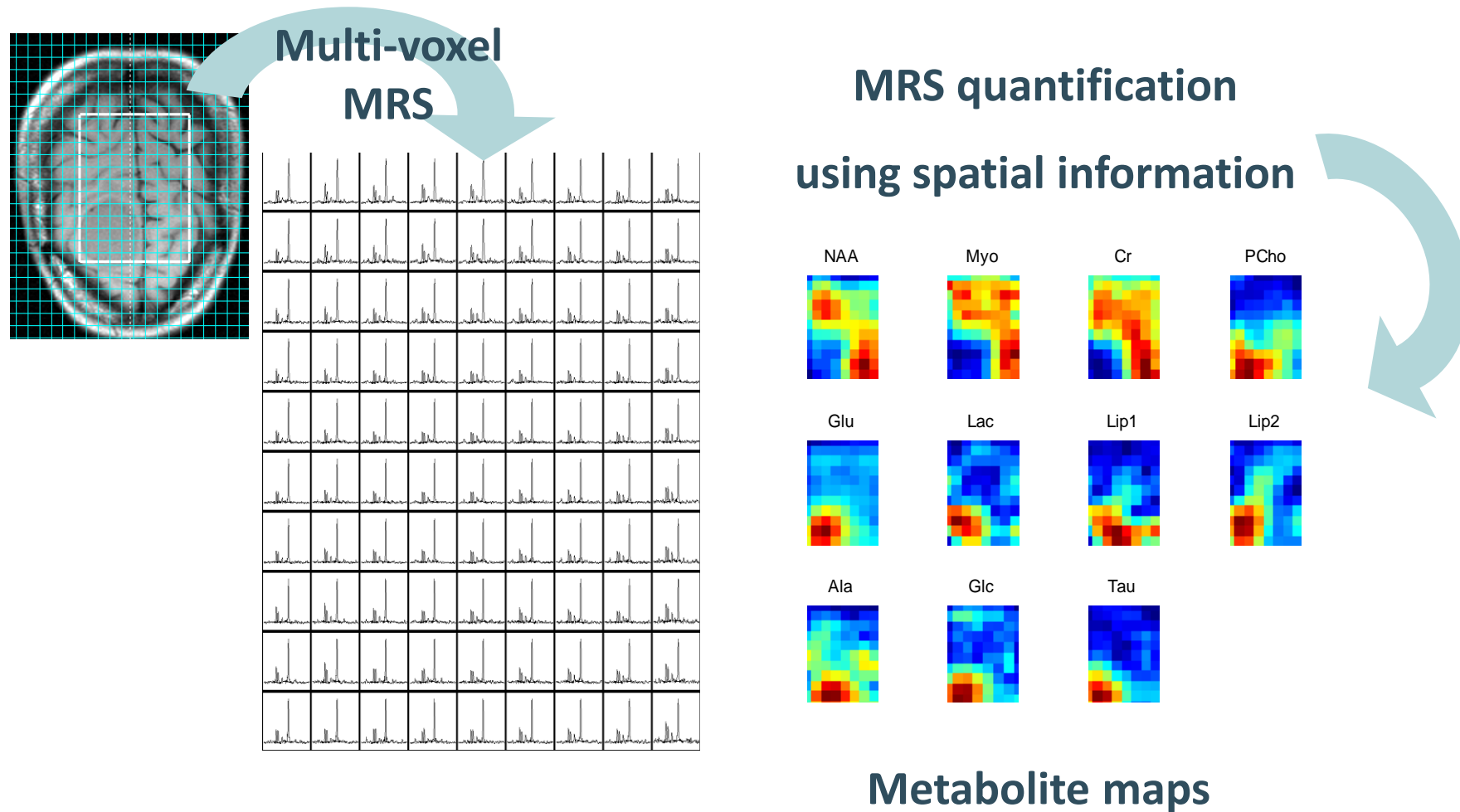
# INTRODUCTION: MRS Acquisition and Purpose



# Metabolite quantification for MR Spectroscopy (MRS)



# Metabolite quantification for MRS Imaging (MRSI)



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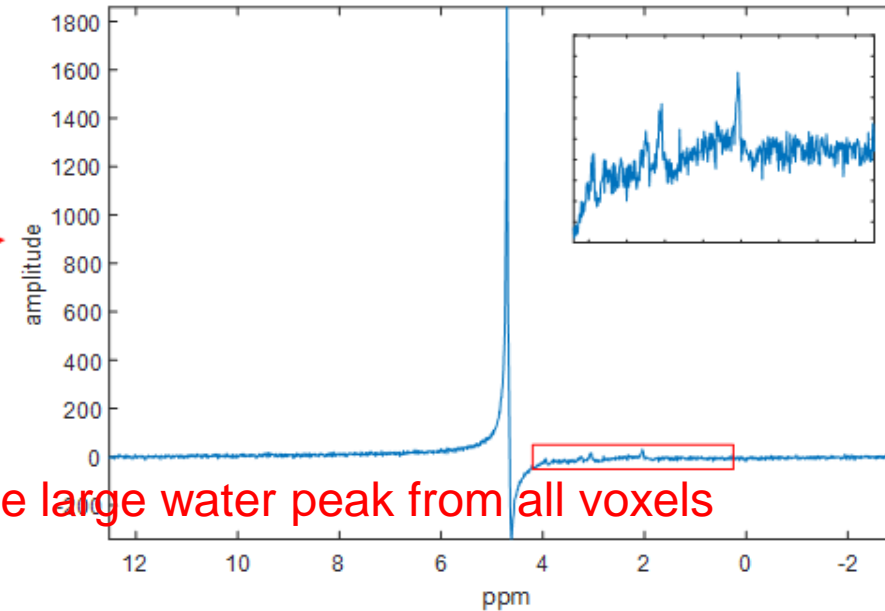
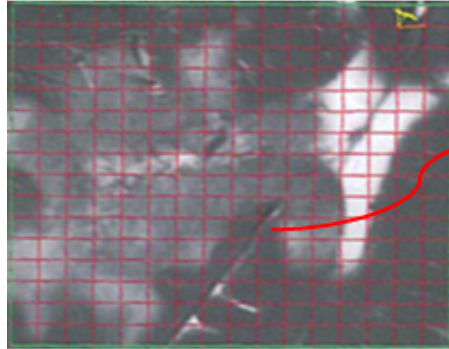


## 4. MRSI tumor voxel classification



## 5. Tumor segmentation from MP-MRI

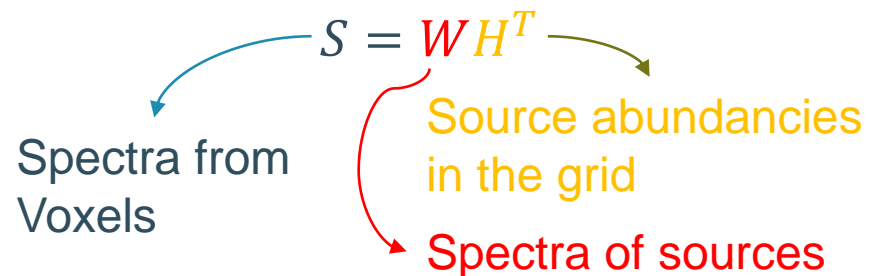
# Introduction- MRSI and water suppression



Aim: Suppress the large water peak from all voxels

Frequency domain Model

$$S(f) = \sum_{r=1}^R \frac{a_r e^{j\phi_r/2\pi}}{d_r + j2\pi(f - f_r)} + \eta(f)$$



Time domain Model

$$S(t) = \sum_{r=1}^R a_r e^{j\phi_r} e^{(-d_r + j2\pi f_r)t} + \eta(t)$$

HSVD based water suppression  
Hankel Tensor + MLSVD



# HSVD based water suppression

- Construct the Hankel matrix  $H$  from the time domain signal  $S$ .
- The Hankel matrix  $H$  has Vandermonde decomposition.

$$H = \begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ z_1^{L-1} & \cdots & z_R^{L-1} \end{bmatrix} \begin{bmatrix} c_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & c_R \end{bmatrix} \begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ z_1^{M-1} & \cdots & z_R^{M-1} \end{bmatrix}^T$$

$a_r e^{j\phi_r}$   $e^{(-d_r + j2\pi f_r)nt}$

- Estimate the parameters  $\{Z \text{ and } C\}$  using SVD.

$$H = USV^H \text{ truncate to } R, H_R = U_R S_R V_R^H$$

- Use the shift-invariance property to estimate the poles.

$$\text{Solve } U_R^\uparrow = U_R^\downarrow T \text{ with } T = Q^{-1} Z Q \text{ and } Z = \text{diag}\{z_1, \dots, z_R\}$$

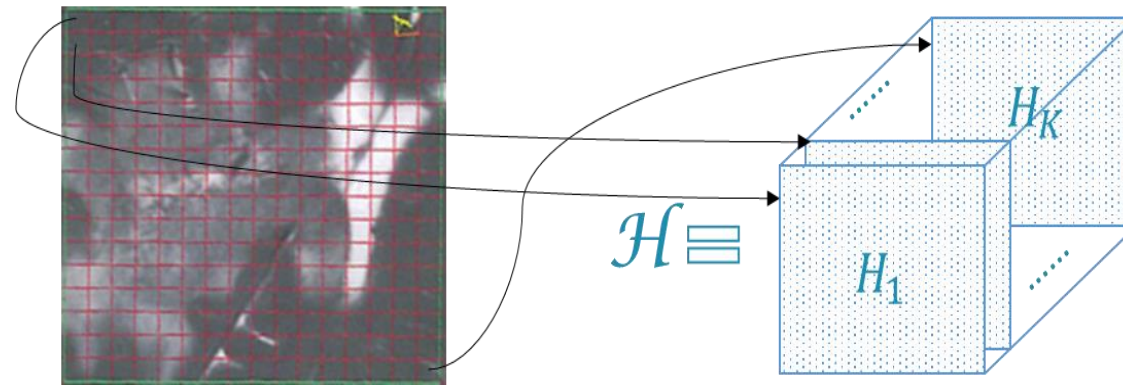
- Poles are estimated as  $z = \text{eig}(Q^{-1} Z Q)$ .

# HSVD based water suppression

- Calculate the amplitudes  $a_k$  from estimated poles and measured signal using least squares.
- Estimate the frequency and damping factor from each pole.
- Estimate the water component using only the poles and amplitudes whose frequencies are outside the region of interest (0.25-4.2 ppm).
- Finally, suppress the water component by subtracting its estimate from the measured signal.
- The disadvantage of this method is that we have to repeat the procedure for all voxels in the MRSI grid.
- **Neighboring voxels have similar water sources with different complex amplitudes → Exploit using tensor approaches.**

# Hankel-tensor based water suppression- MLSVD

- Each individual component can be well approximated by complex-damped exponentials.
- For each voxel in the MRSI, construct a Hankel matrix from the free induction decay (FID) signal but now stack these to form a tensor.



- Parameters of the complex-damped exponentials can be obtained using MLSVD

$$\mathcal{H} = \mathcal{A} \times_1 U^{(1)} \times_2 U^{(2)} \times_3 U^{(3)}$$

# Hankel based water suppression- MLSVD

- The frequency and damping of individual sources can be obtained using shift-invariance property and eigen-value decomposition of mode-1 factor matrix  $U^{(1)}$ .
- Water sources are estimated by reconstructing those exponentials outside the region of interest (0.25-4.2 ppm).
- The total water component (including amplitudes) is estimated by fitting those water exponentials to the measured signal using least-squares.
- Finally, the water component is suppressed by subtracting this estimated water signal from the measured MRSI signal.

# Löwner based water suppression

$$S(f) = \sum_{r=1}^R \frac{a_r e^{j\phi_r/2\pi}}{d_r + j2\pi(f - f_r)} + \eta(f)$$

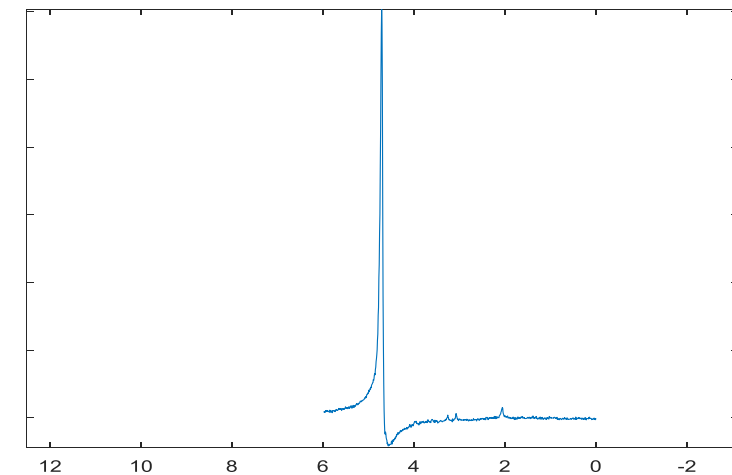
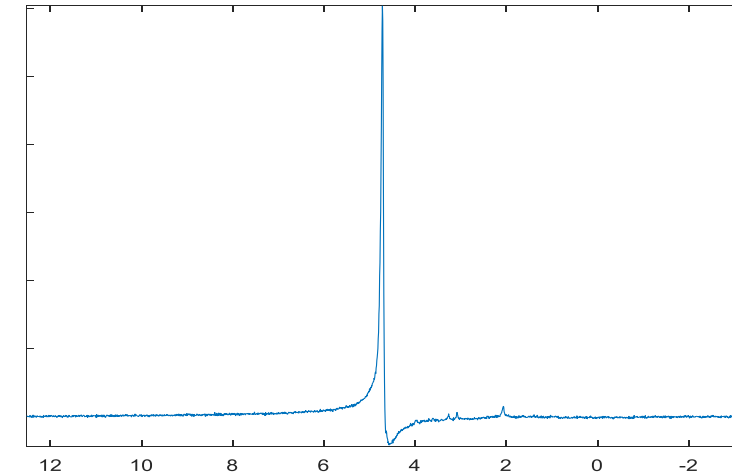
- For each voxel in the MRSI signal construct a Löwner matrix from truncated spectrum  $S_{wr}$ .

$$L = \begin{bmatrix} \frac{S_{wr}(x_1) - S_{wr}(y_1)}{x_1 - y_1} & \dots & \frac{S_{wr}(x_1) - S_{wr}(y_J)}{x_1 - y_J} \\ \vdots & \ddots & \vdots \\ \frac{S_{wr}(x_I) - S_{wr}(y_1)}{x_I - y_1} & \dots & \frac{S_{wr}(x_I) - S_{wr}(y_J)}{x_I - y_J} \end{bmatrix}$$

Using interleaved partitioning in two point sets X and Y:

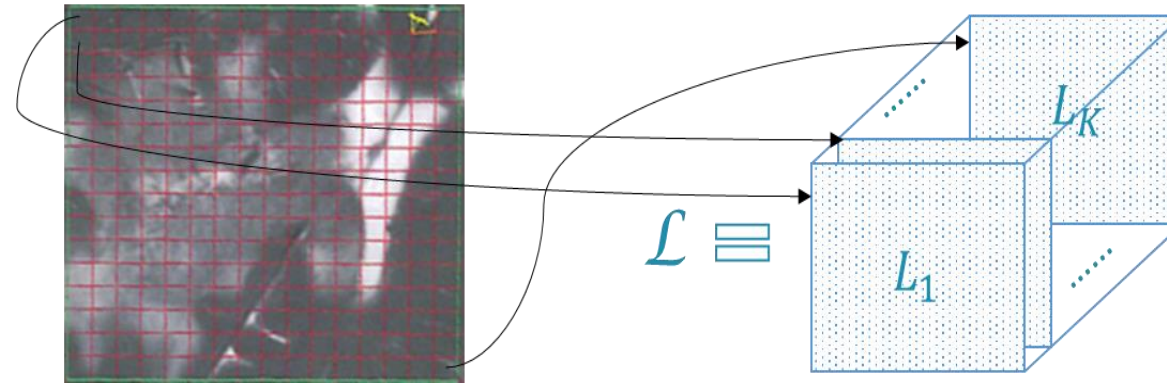
$$X = \{x_1, x_2 \dots\} \rightarrow \{1, 3, \dots\} \text{ and } Y = \{y_1, y_2 \dots\} \rightarrow \{2, 4, \dots\}$$

- If a Löwner matrix  $L$  is constructed from a rational function of degree  $R$ , the matrix  $L$  has rank  $R$ .



# Löwner based water suppression- CPD

- For each voxel in the MRSI signal construct a Löwner matrix from the spectra and stack these to form a tensor.



- Each individual component can be well approximated by a degree-1 rational function, hence BSS reduces to CPD.

$$\mathcal{L}_S \approx \sum_{r=1}^R a_r \otimes b_r \otimes h_r, \quad L_R = a_r b_r^T$$

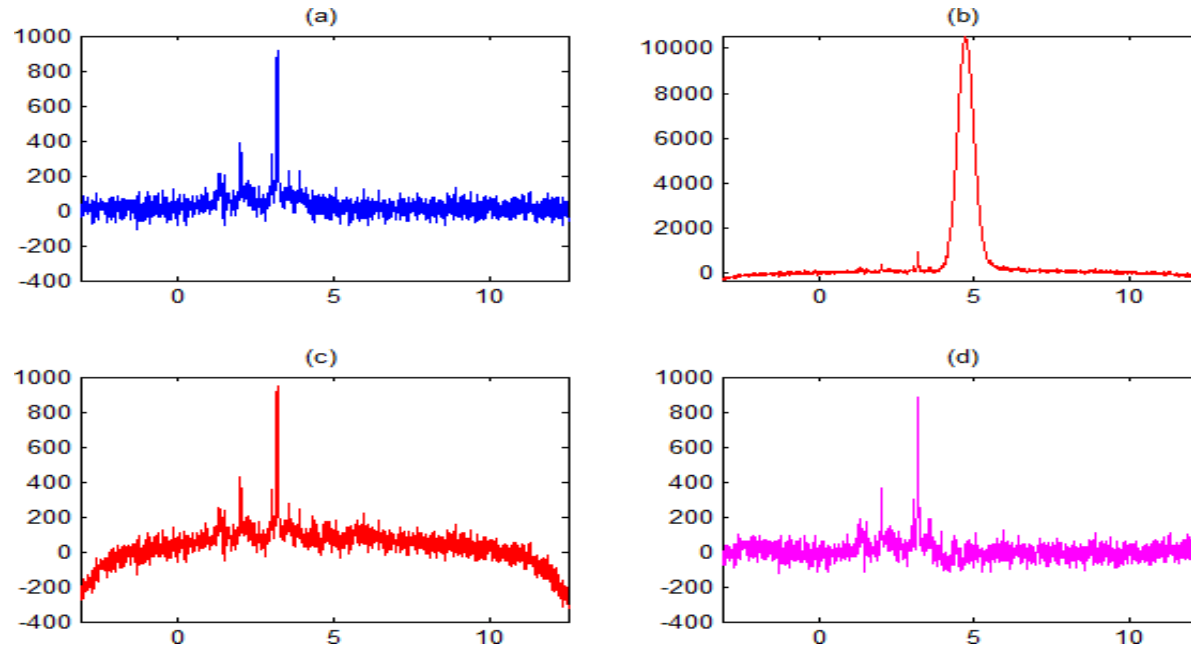
# Löwner based water suppression

$$L_r = A(:, r)B(:, r)^T$$
$$A(:, r) = \begin{bmatrix} \frac{a_{r1}}{(ix_1 + b_r)} \\ \vdots \\ \frac{a_{k1}}{(ix_I + b_r)} \end{bmatrix}, \quad B(:, k)^T = \left[ \frac{a_{r2}}{(iy_1 + b_r)} \quad \cdots \quad \frac{a_{r2}}{(iy_J + b_r)} \right]$$
$$a_r = a_{r1} * a_{r2}$$

- Parameters  $a_{k1}$ ,  $a_{k2}$  and  $b_k$  are estimated using least squares from  $A(:, k)$  and  $B(:, k)$ .
- Water component is estimated using only the sources and amplitudes that are outside the region of interest (0.25-4.2 ppm).
- Finally the water component is suppressed by subtracting the estimated water signal from the measured signal.

# Löwner based water suppression- Baseline

- Problem: In some voxels, water suppression will result in a baseline at the edges of the spectra.



- Solution: Model the baseline using polynomial function and add it to the source matrix  $W$ .

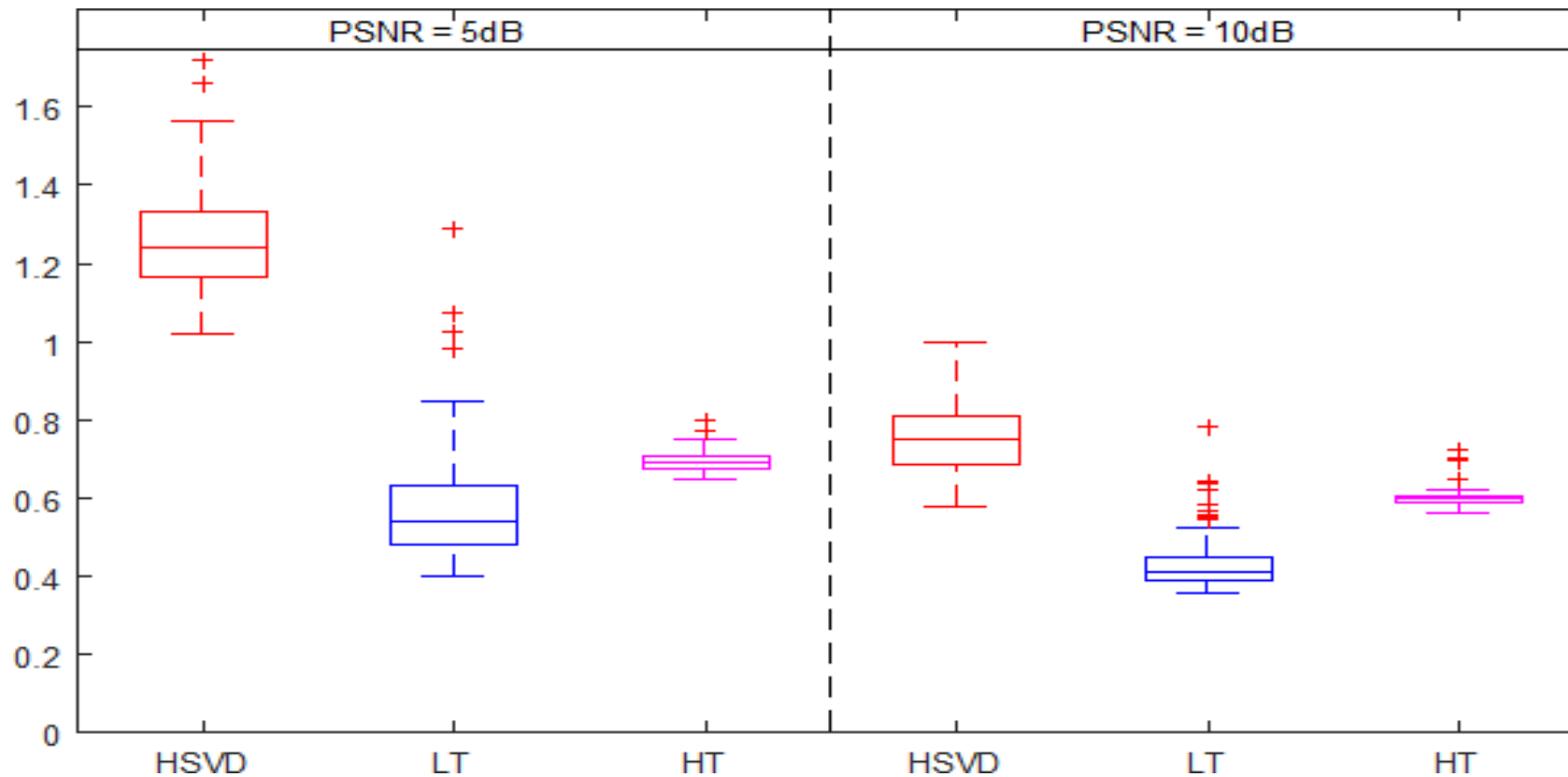
$$W_{poly} = \begin{bmatrix} w_{11} & \cdots & w_{1R} & 1 & \cdots & f_1^d \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ w_{N1} & \cdots & w_{NR} & 1 & \cdots & f_N^d \end{bmatrix}$$



# Hankel based water suppression- Results

Simulation:

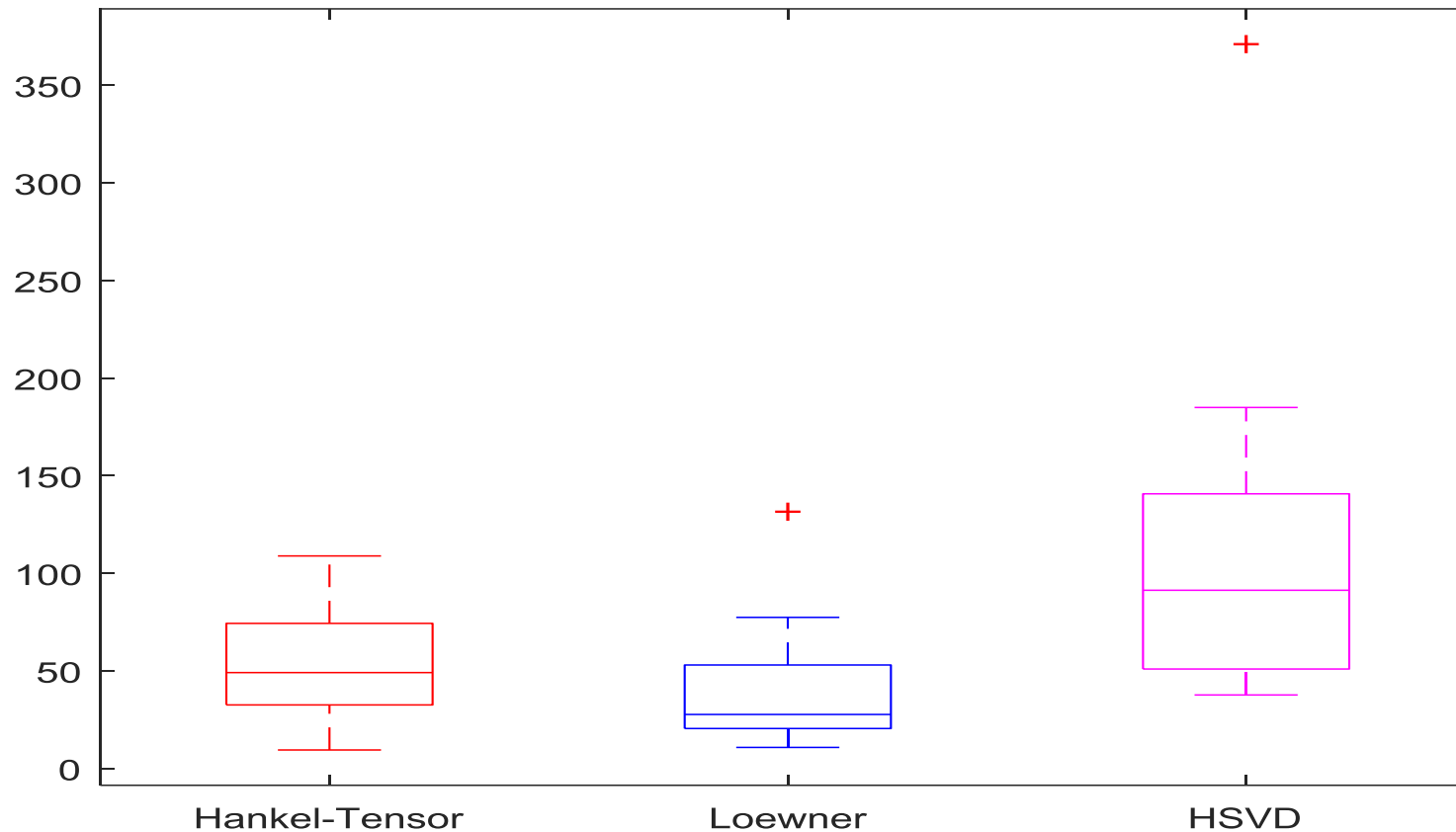
- Metabolite spectra generated using in-vitro signals.
- Residual water generated using scaled water reference signal measured in-vivo.



Box-plot of errors on simulated MRSI data

# Hankel based water suppression- Results

- Water suppression methods are tested on 28 in-vivo measured MRSI signals.



Box-plot displays differences in variance in suppressed region of the in-vivo MRSI data

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- From MP-MRI

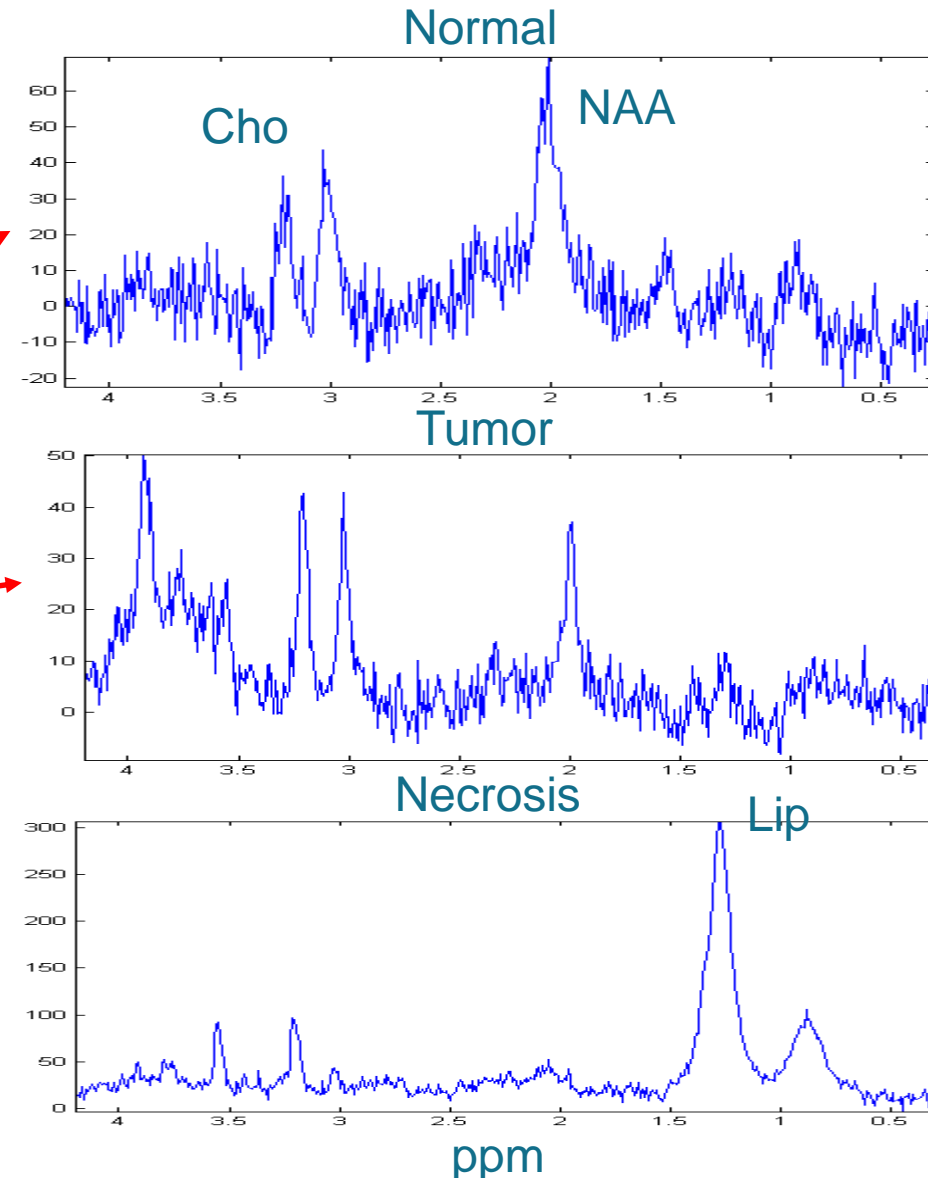
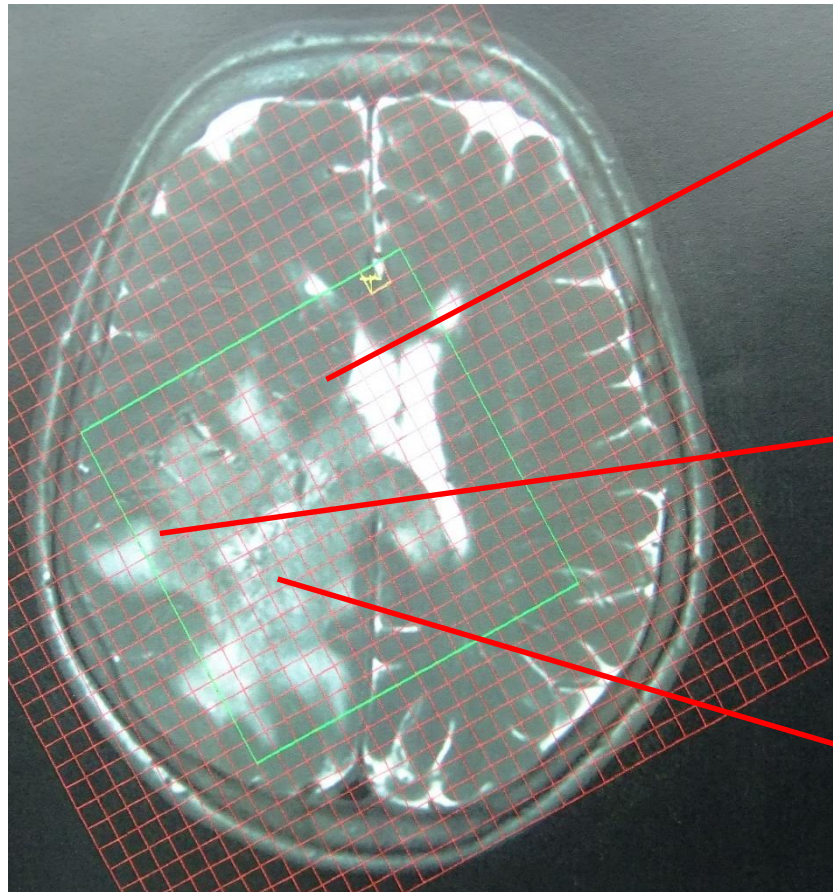


## 4. MRSI tumor voxel classification

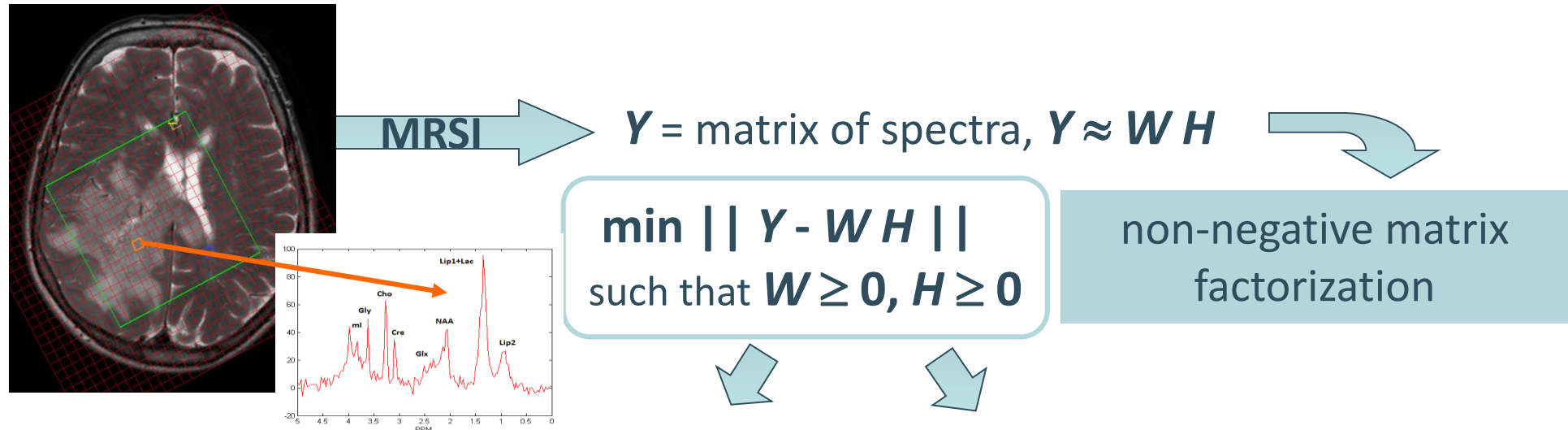


## 5. Tumor segmentation from MP-MRI

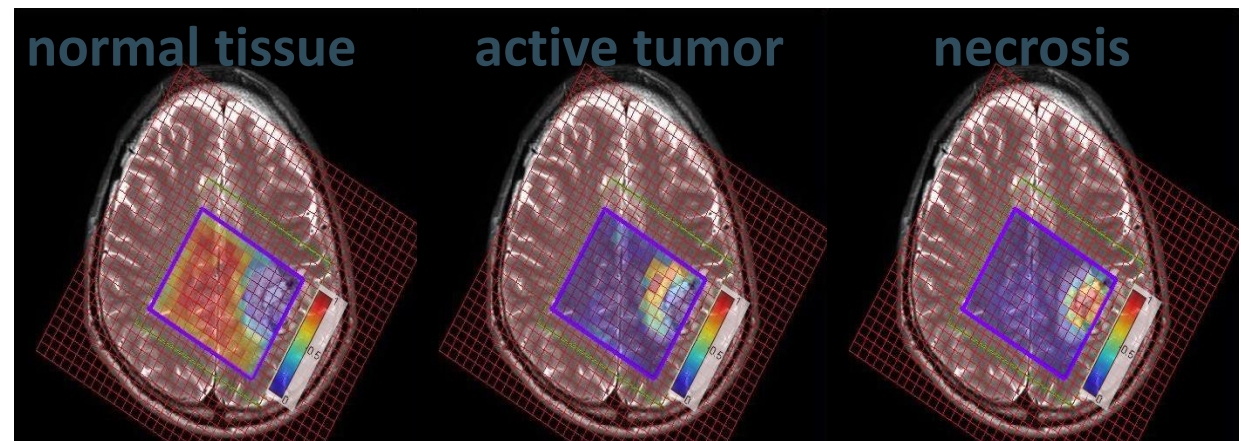
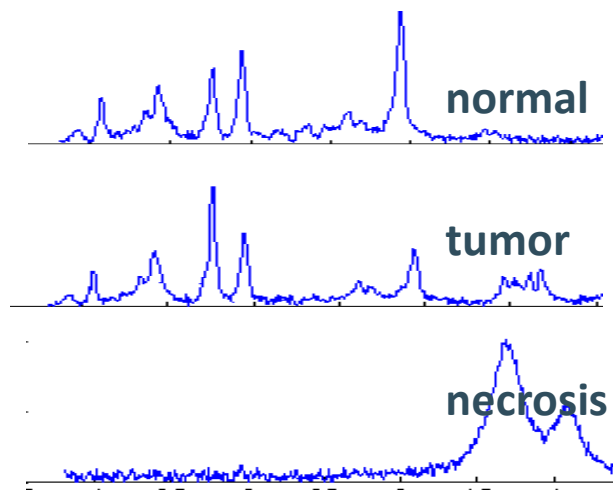
# Gliomas- Pathologic tissue spectrum



# Unsupervised Brain Tumor Diagnosis using NMF

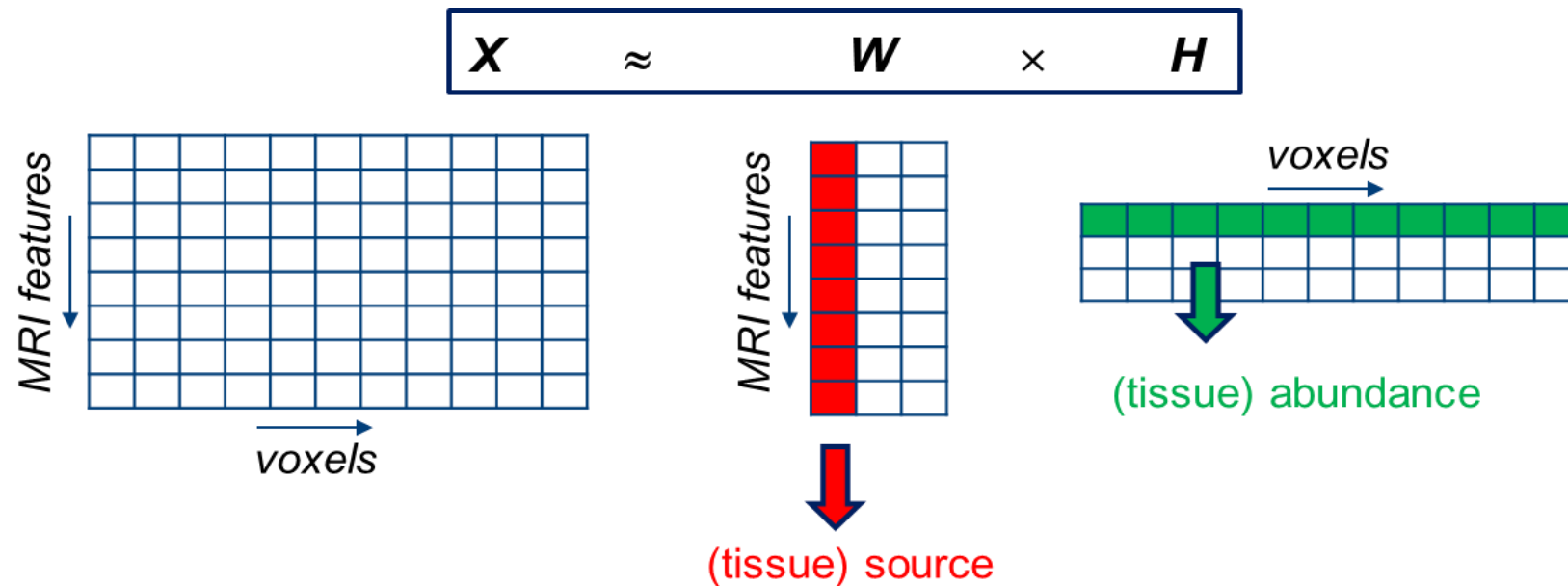


$W$  = tissue-specific spectral patterns:      spatial distribution of tissue types:



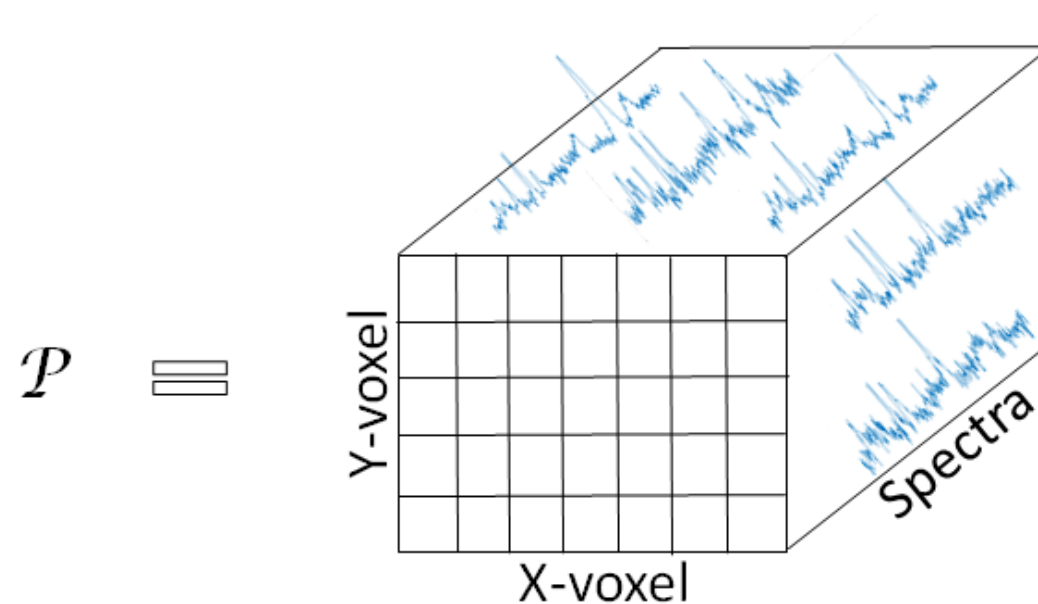
glioblastoma multiforme patient

# Non-negative matrix factorization (NMF)



- Non-negativity constraint:  $X_{i,j}, W_{i,j}, H_{i,j} \geq 0, \forall i,j$ 
  - Columns of  $\mathbf{W}$  ~ sources (tissue signatures)
  - Rows of  $\mathbf{H}$  ~ source abundances (tissue weights)
- Unsupervised: directly applicable patient-by-patient, but tissue classes not a priori known

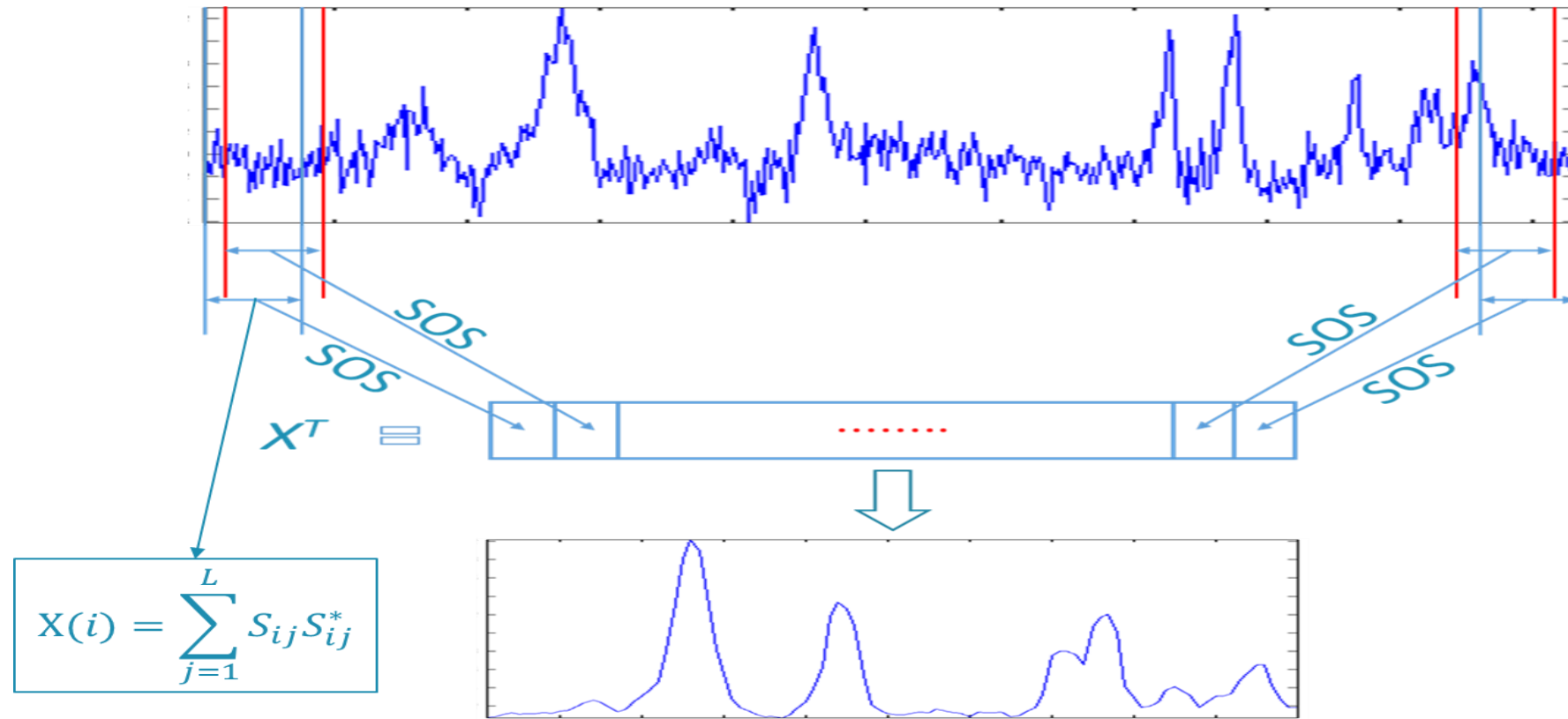
# Spatial MRSI tensor



- Use rank- $(L_r, L_r, 1)$  block term decomposition to estimate tissue specific spectra and their corresponding distribution.
  - Tissue distribution may not be of low rank.
  - Difficult to estimate the rank  $L_r$  for each term.



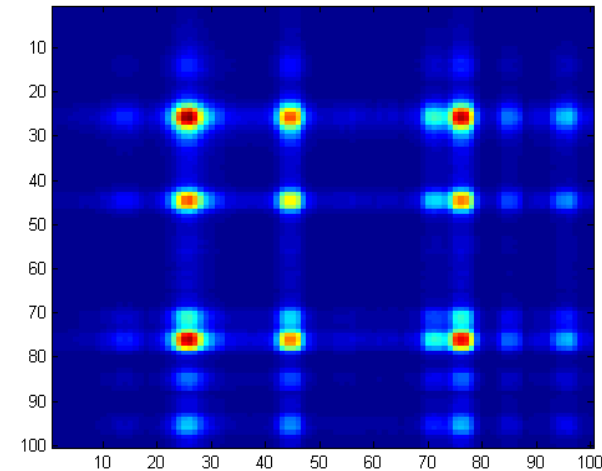
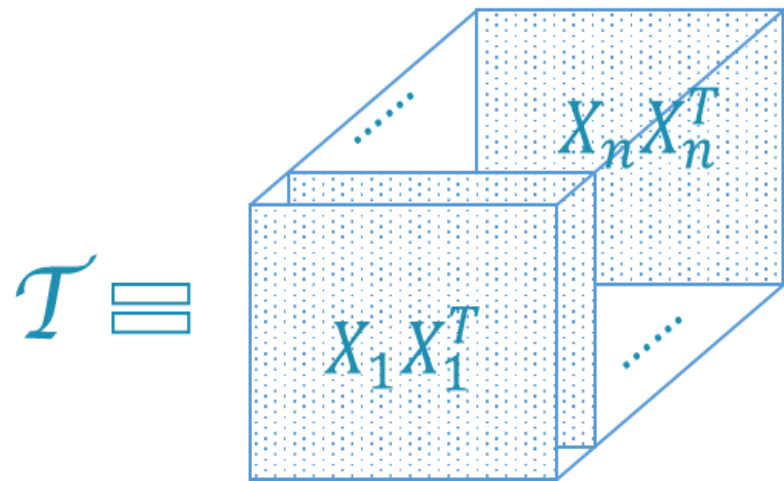
# Tissue type differentiation from MRSI



- Reduces the length of spectra without losing vital information required for tumor tissue type differentiation.
- This preprocessing gives more weight to the peaks and makes the signal smoother.

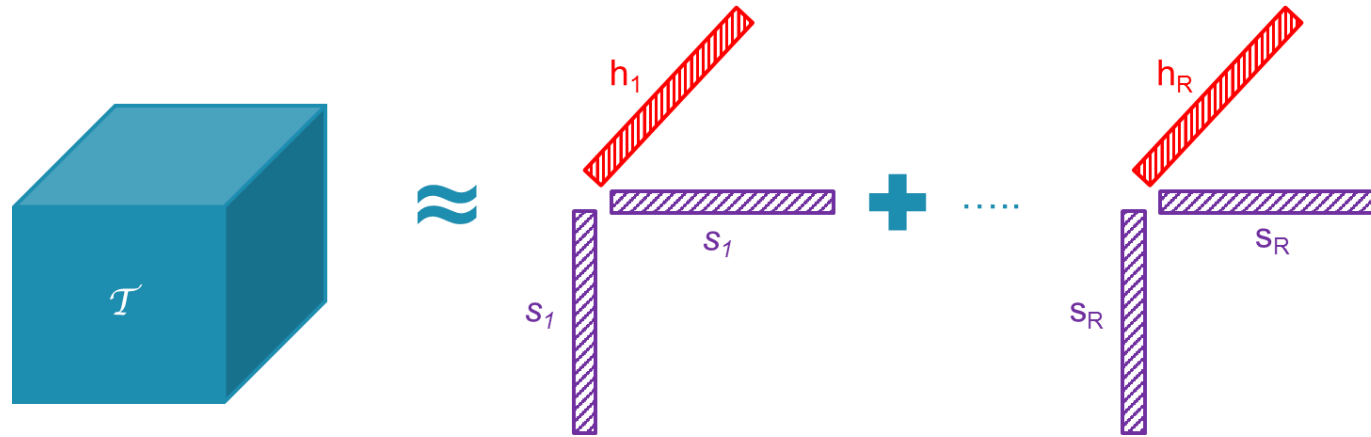


# Tissue type differentiation from MRSI- $XX^T$ tensor



- Construct a 3-D tensor by stacking  $XX^T$  from each voxel.
- MRSI tensor couples the peaks in the spectra because of the  $XX^T$  in the frontal slices.

# Tissue type differentiation from MRSI: NCPD



- Non-negative constraint is applied on all 3-modes.
- To maintain symmetry in frontal slices common factor (S) is used in both mode 1 and mode 2.

$$T \approx [S, S, H] = \sum_{r=1}^K S(:, r) \circ S(:, r) \circ H(:, r)$$

- Non-negative CPD is performed in Tensorlab toolbox using structured data fusion.

# $l_1$ Regularized NCPD

- Here, we assume that spectra corresponding to each voxel belongs to a particular tissue type, therefore the factor matrix  $H$  will be sparse.
- Non-negative CPD with  $l_1$  regularization on the abundances  $H$ .

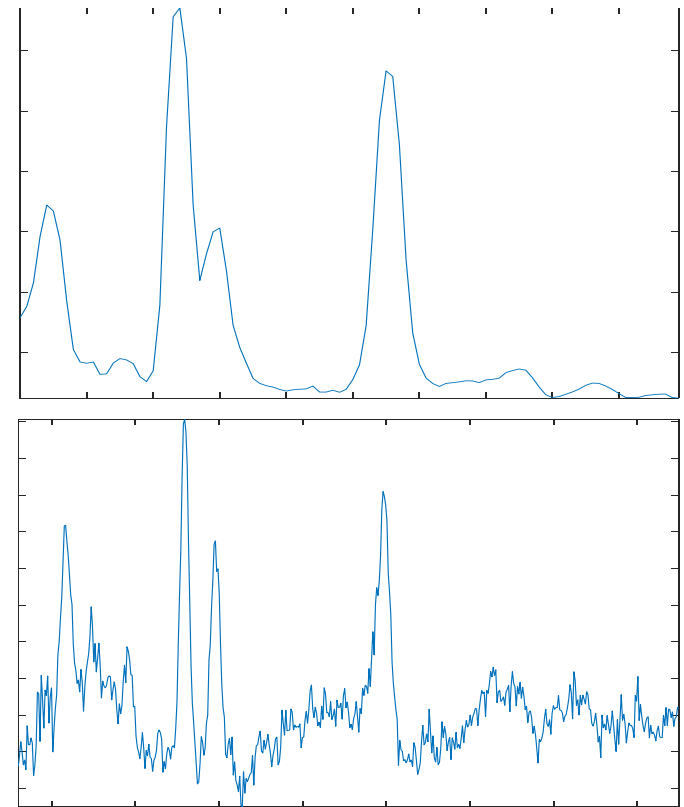
$$[S^*, H^*] = \min_{S, H} \left\| T - \sum_{r=1}^K S(:, r) \circ S(:, r) \circ H(:, r), \right\|_2^2 + \lambda |Vec(H)|_1$$

where  $\lambda$  controls the sparsity in  $H$ .

- Use more sources (higher rank) to accommodate for artifacts and variations within tissue types.
- Original source spectra are recovered using least squares:

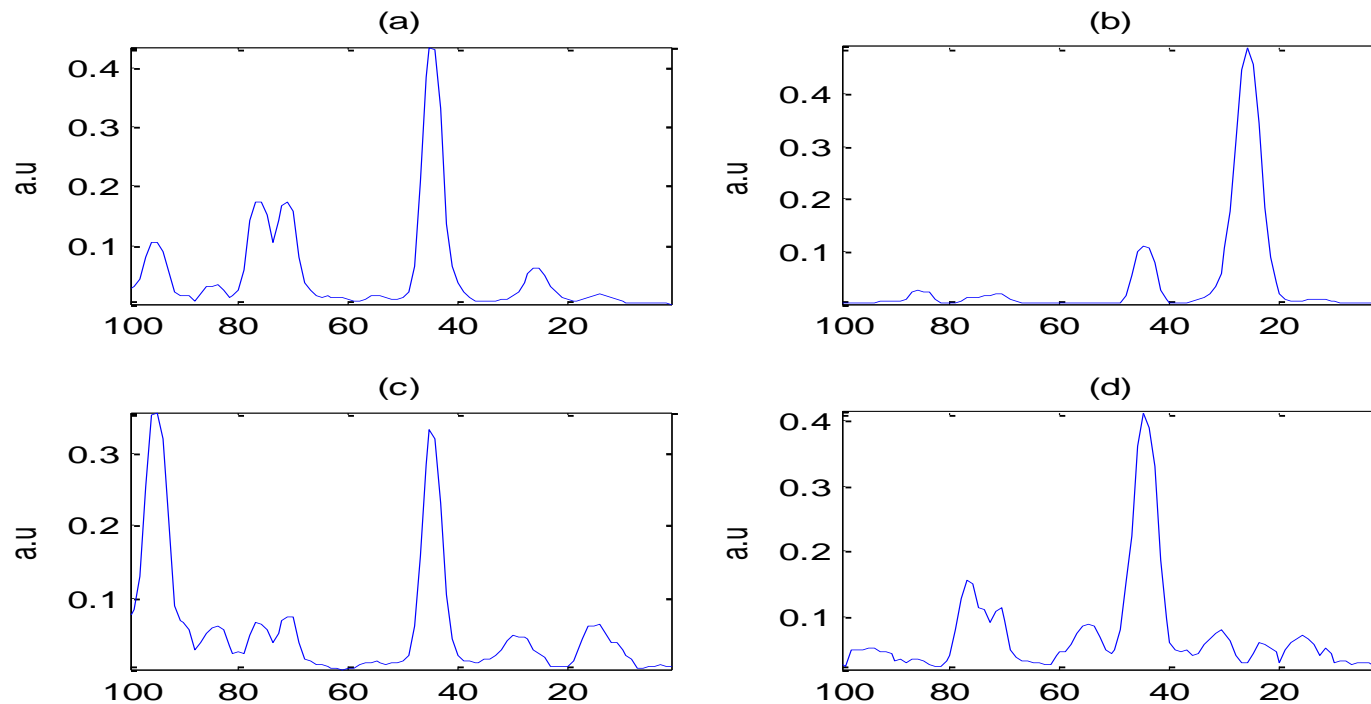
$$S = (H^\dagger Y^T)^T$$

$H^\dagger$  is the pseudo-inverse of  $H$  obtained from Non-negative CPD.



# Initialization

- Take SVD of the complex spectra,  $Y = U\Sigma V^H$ .
- Construct the reduced spectrum from  $R$  dominant singular vectors. Use this to initialize  $S$  in the NCPD.
- $H$  in NCPD is initialized using least squares,  $H_{init} = (S_{init}^\dagger A)^T$ .



# Rank estimation

- Estimate the covariance matrix from the reduced spectra data matrix,  $A$ .

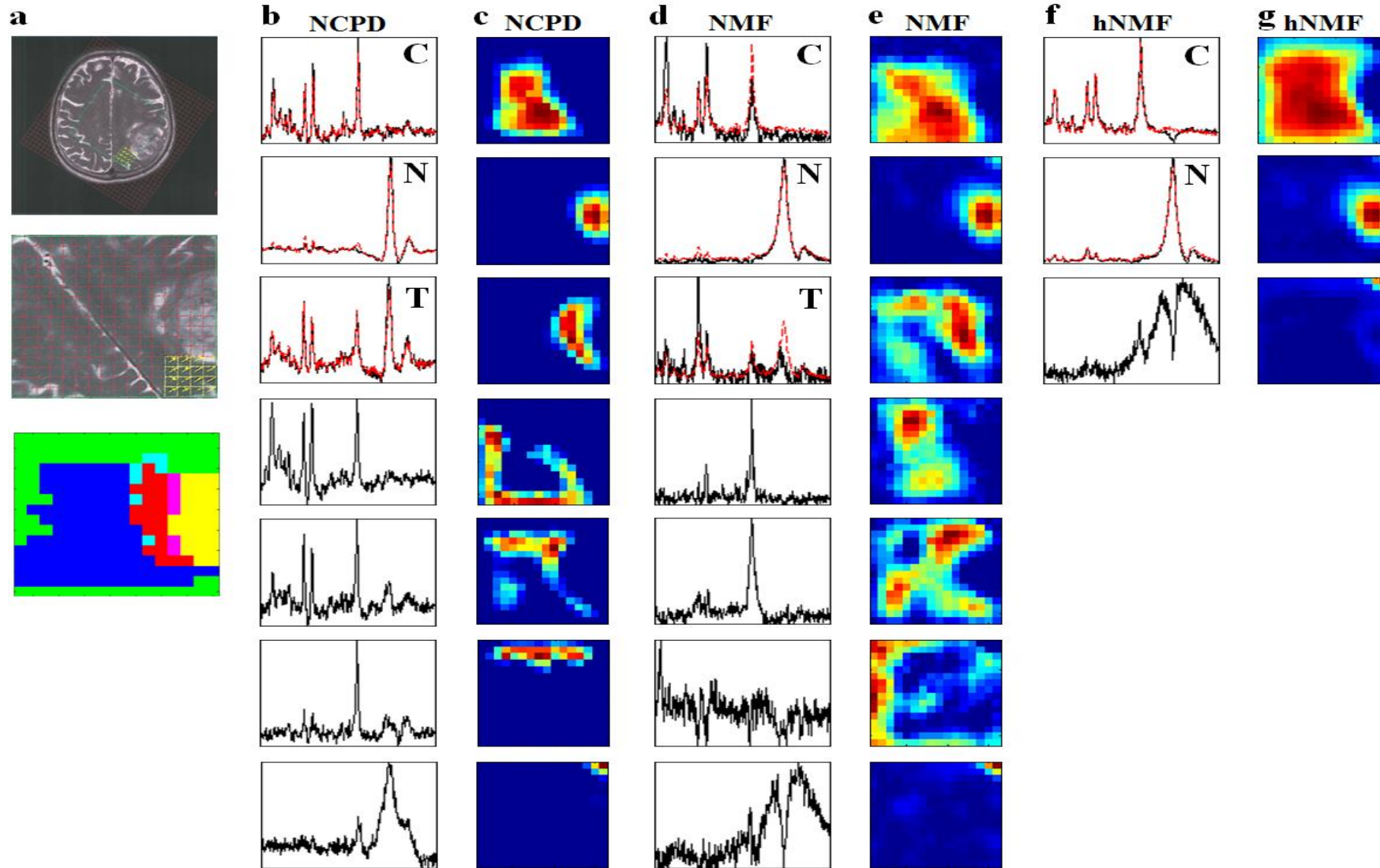
$$C = E[(A - E[A])(A - E[A])^T]$$

- The number of sources is estimated as the minimum number  $R$  such that the cumulative sum of eigenvalues represents at least 99% of the total energy.

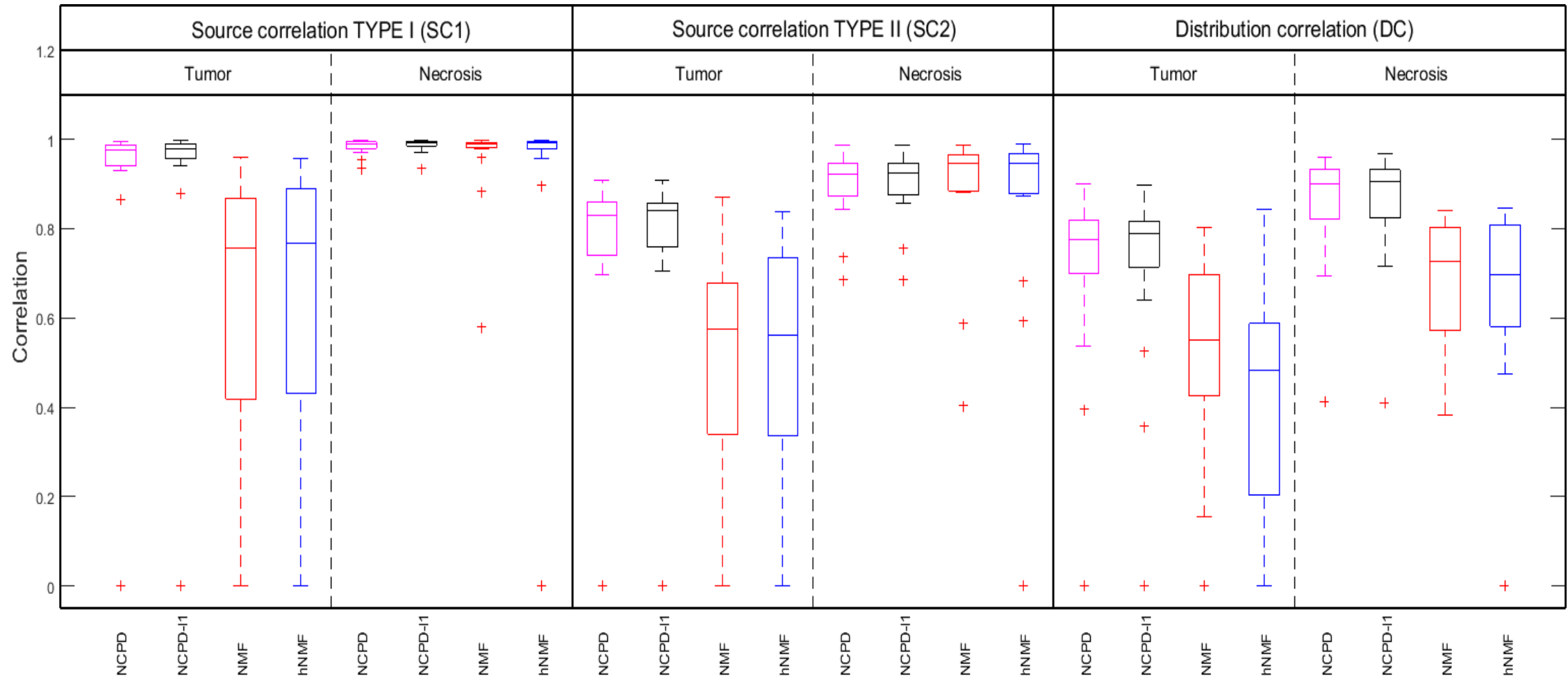
$$R^* = \arg \min_R \left[ \frac{\sum_{i=1}^{i=R} \lambda_i}{\sum_{i=1}^{i=K} \lambda_i} \geq 0.99 \right]$$

- Incorporate prior knowledge about the maximum number of sources ( $R \leq 8$ ).

# Tissue type differentiation from MRSI- Results

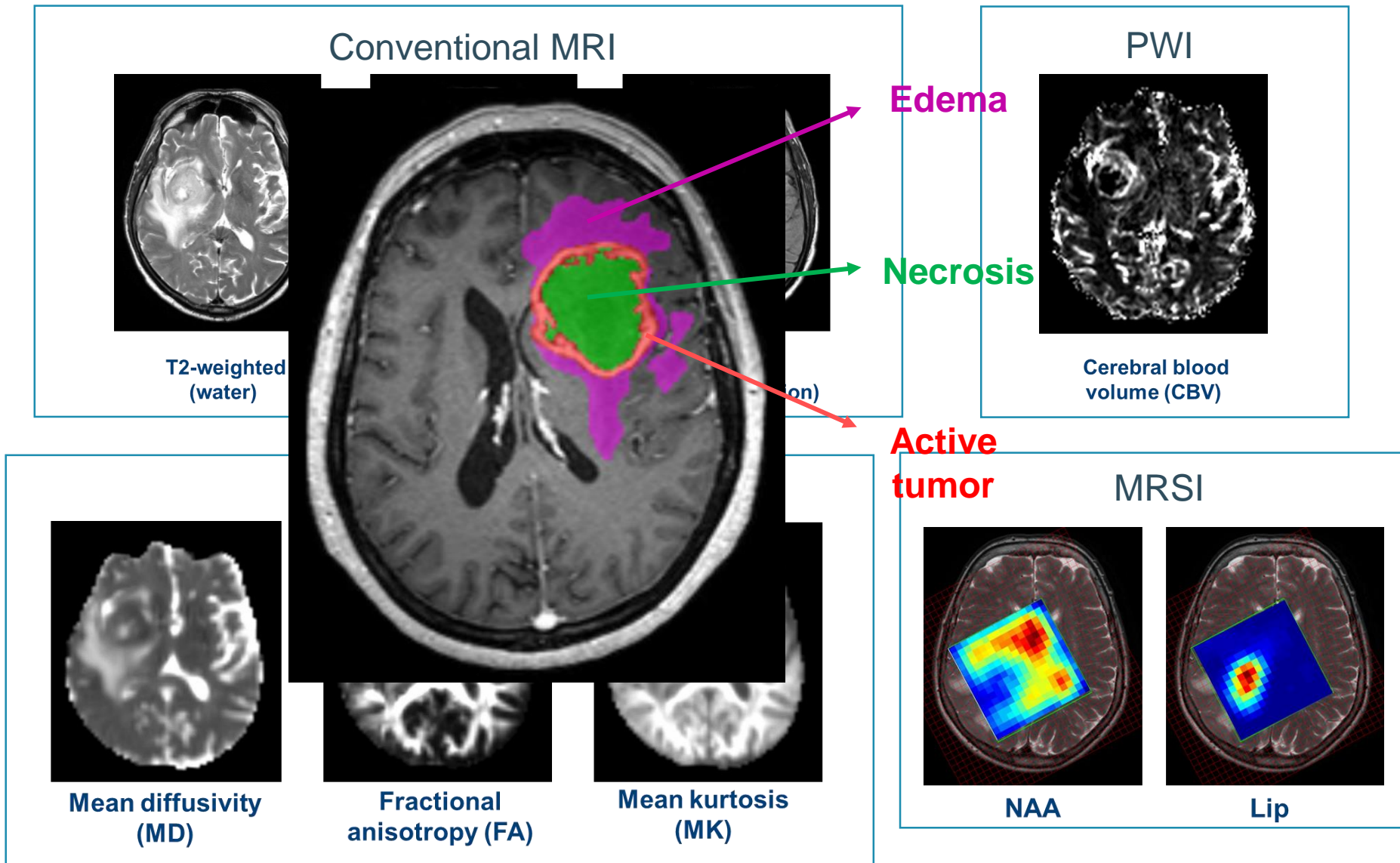


# Tissue type differentiation from MRSI- Results





# Tissue type differentiation from MultiParametric (MP)-MRI\*





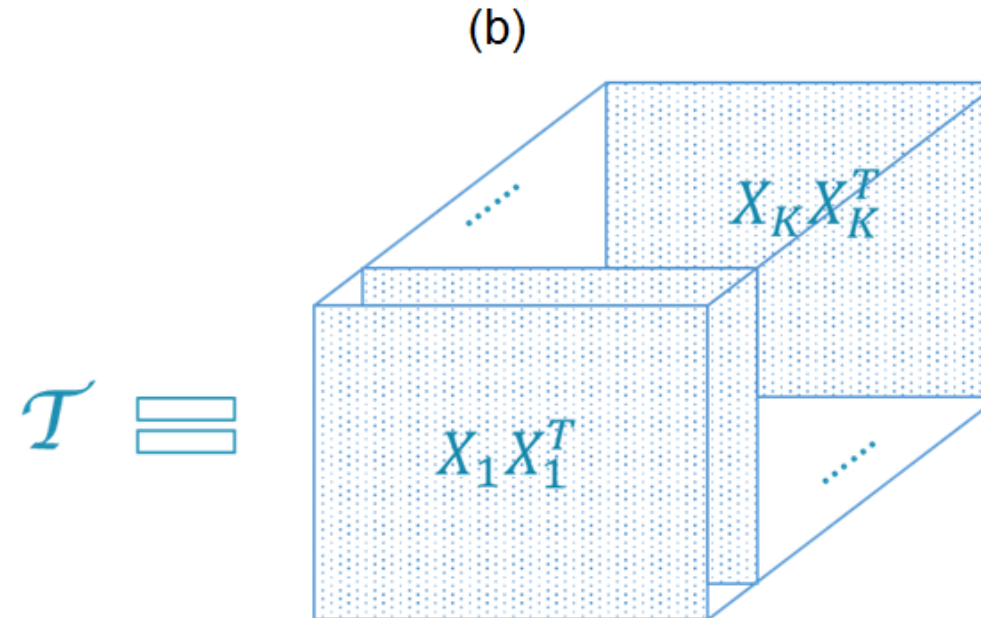
# Tissue type differentiation from MP-MRI:- $XX^T$ tensor

(a)

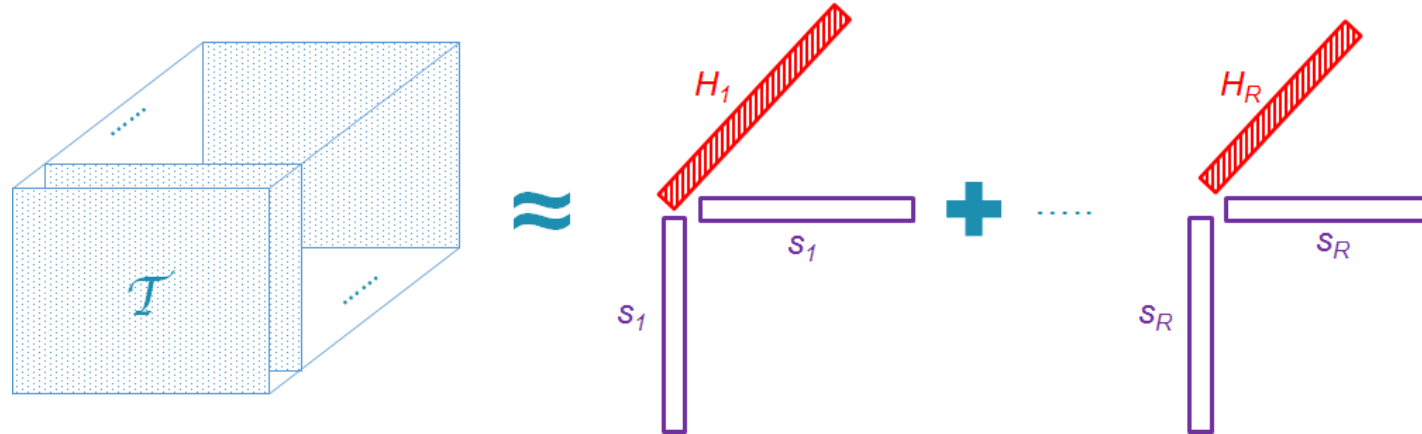
$X \equiv$

FA(3x3)
FA(3x3)
MK(5x5)
MK(3x3)
MD(5x5)
MD(3x3)
rCBV(5x5)
rCBV(3x3)
FLAIR(5x5)
FLAIR(3x3)
T1+C(5x5)
T1+C(3x3)
T2(5x5)
T2(3x3)
FA
MK
MD
rCBV
FLAIR
T1+C
T2
Lip
Lac
NAA
Glx
Cre
Cho
Gly
ml

$T$



# Tissue type differentiation from MP-MRI:- CPD

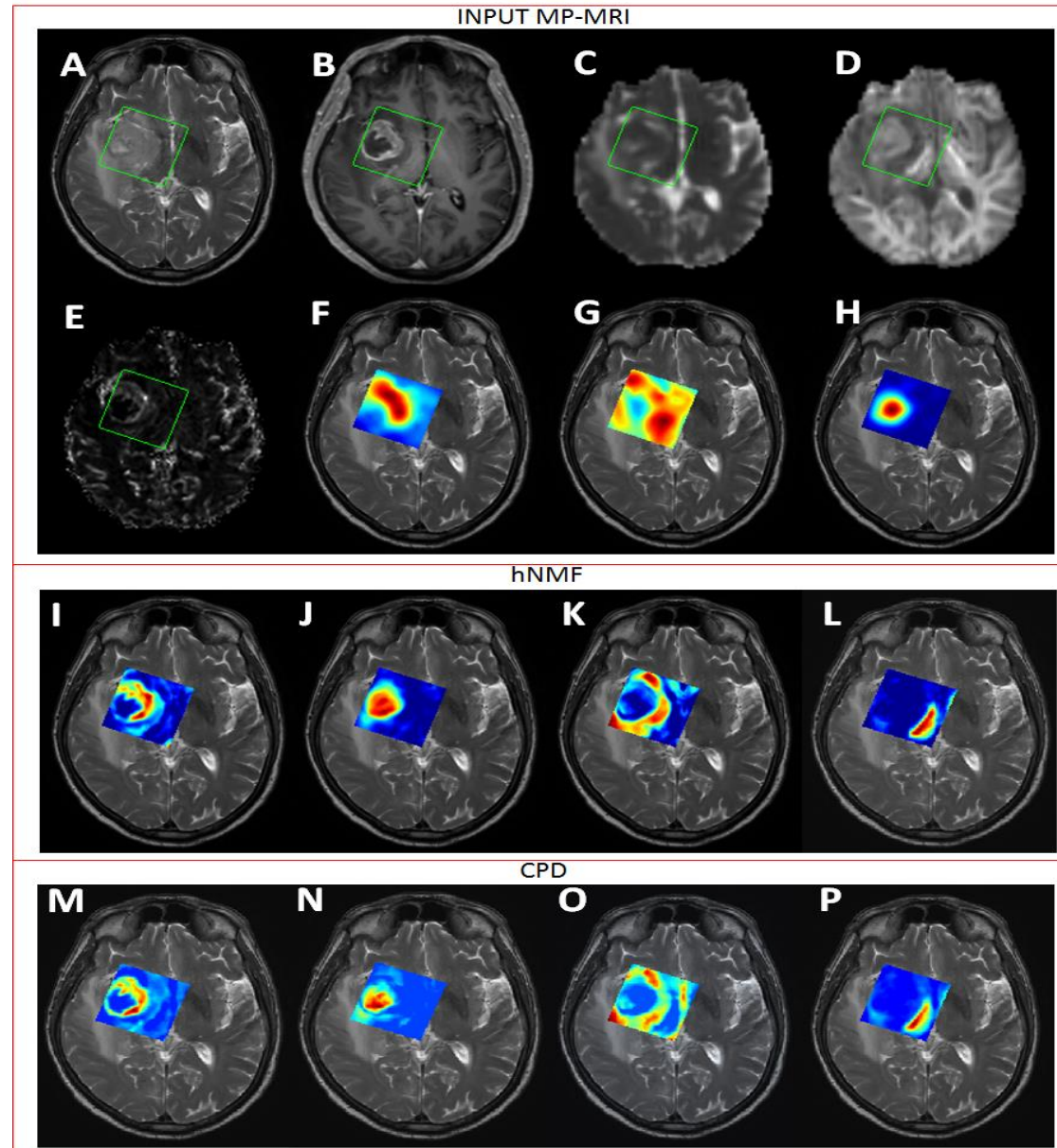


- To maintain symmetry in frontal slices common factor ( $S$ ) is used in both mode-1 and mode-2.
- Non-negative constraint is applied on mode-3,  $H$ .
- Also,  $l_1$  regularization is applied on the abundances  $H$ .

$$[S^*, H^*] = \arg \min_{S, H \geq 0} \left\| \mathcal{T} - \sum_{i=1}^R S(:, i) \circ S(:, i) \circ H(:, i) \right\|_2^2 + \lambda \|Vec(H)\|_1$$

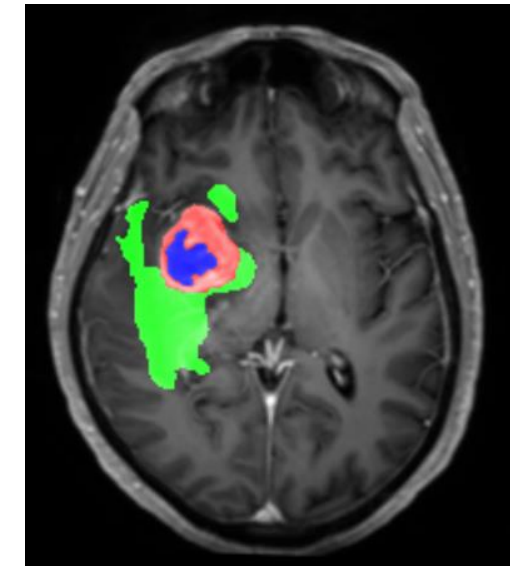
- Solve using structured data fusion method in Tensorlab.

# Results:



# Segmentation accuracy

Based on manual segmentation by radiologist  
(for pathological tissue types)

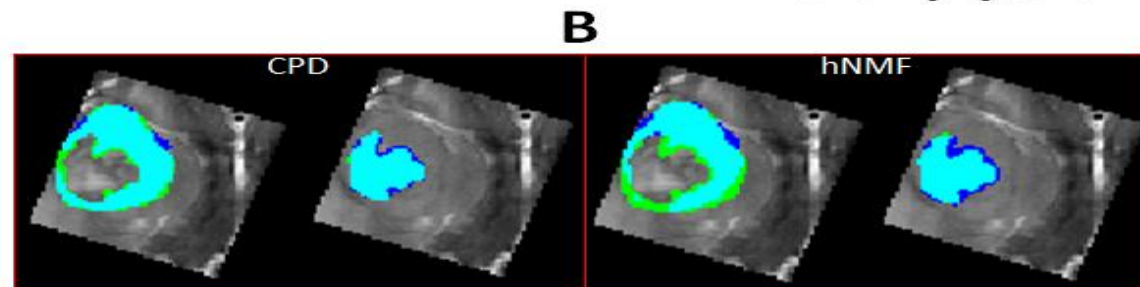
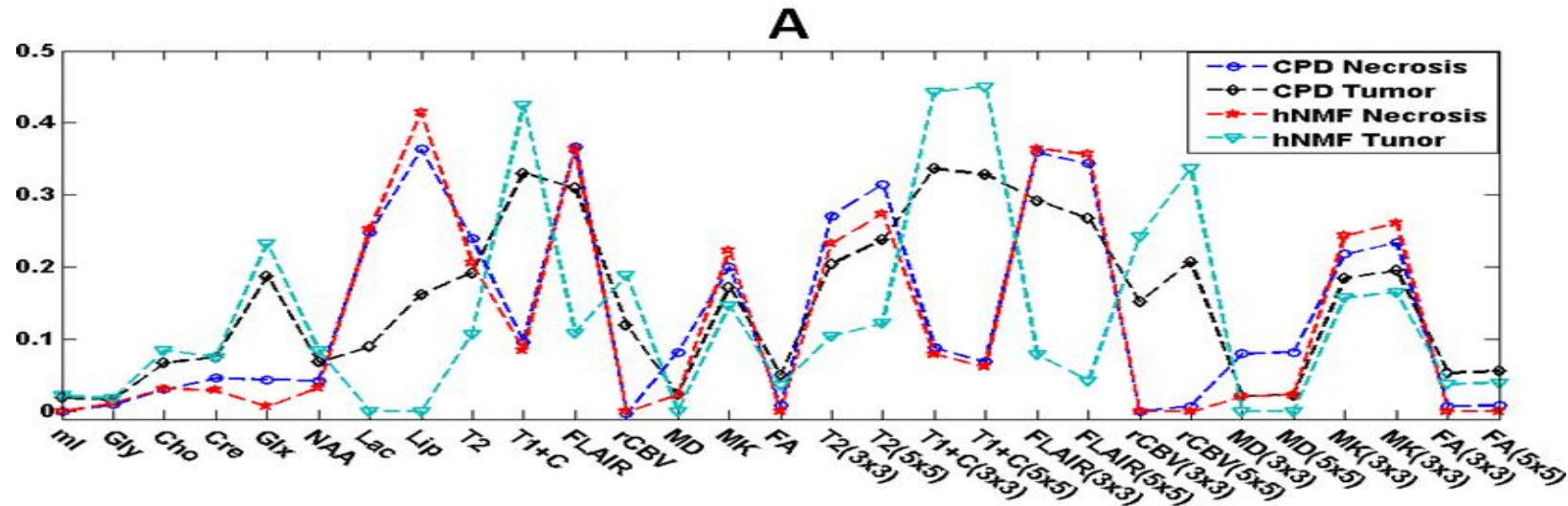


## 1) Dice-scores\* (based on H)

$$Dice = \frac{2 * area(A \cap B)}{area(A) + area(B)}$$



# Tissue type differentiation from MP-MRI:- results



	Constrained CPD- $I_1$			hNMF		
	Dice Tumor	Dice Core	Tumor source Correlation	Dice Tumor	Dice Core	Tumor source Correlation
Mean	0.83	0.87	0.95	0.78	0.85	0.81
Standard deviation	0.07	0.1	0.05	0.09	0.13	0.19

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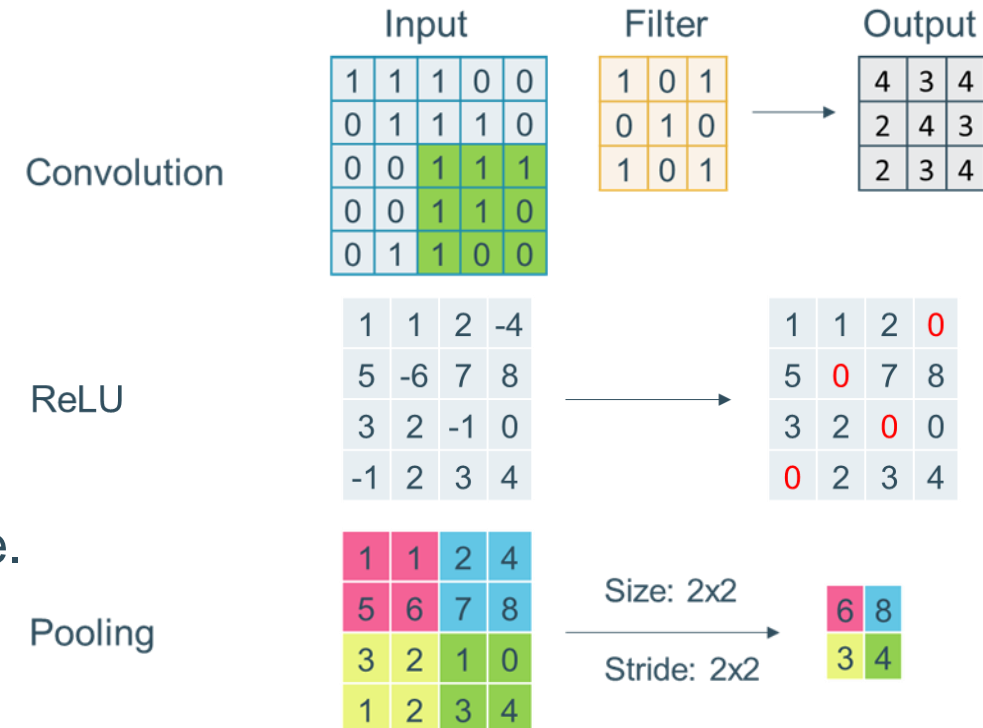
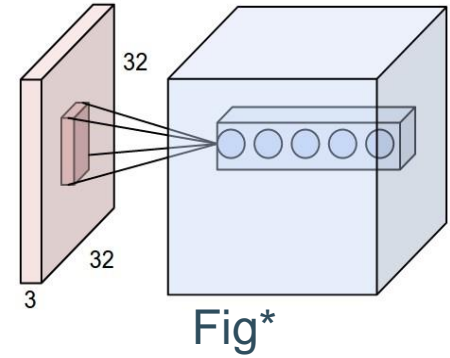


## 5. Tumor segmentation from MP-MRI

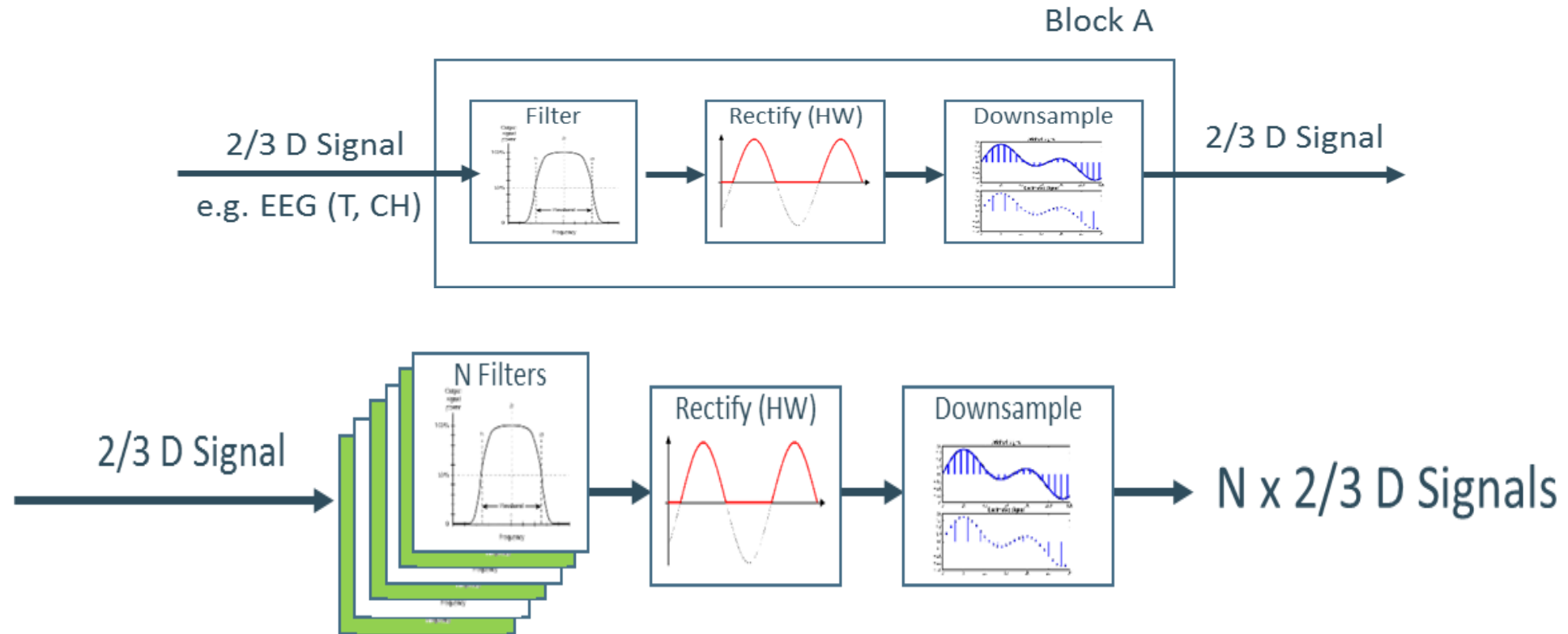


# Tumor classification: CNN

- Convolutional neural network is a class of deep neural networks. Exploit spatial locality with shared weights.
- Three main layers
  - Convolutional layer:
    - Performs 2-D convolution
  - ReLU:
    - Applies non-linear activation function.
  - Pool:
    - Values over a window are reduced to a single value.



# Convolutional Neural Network

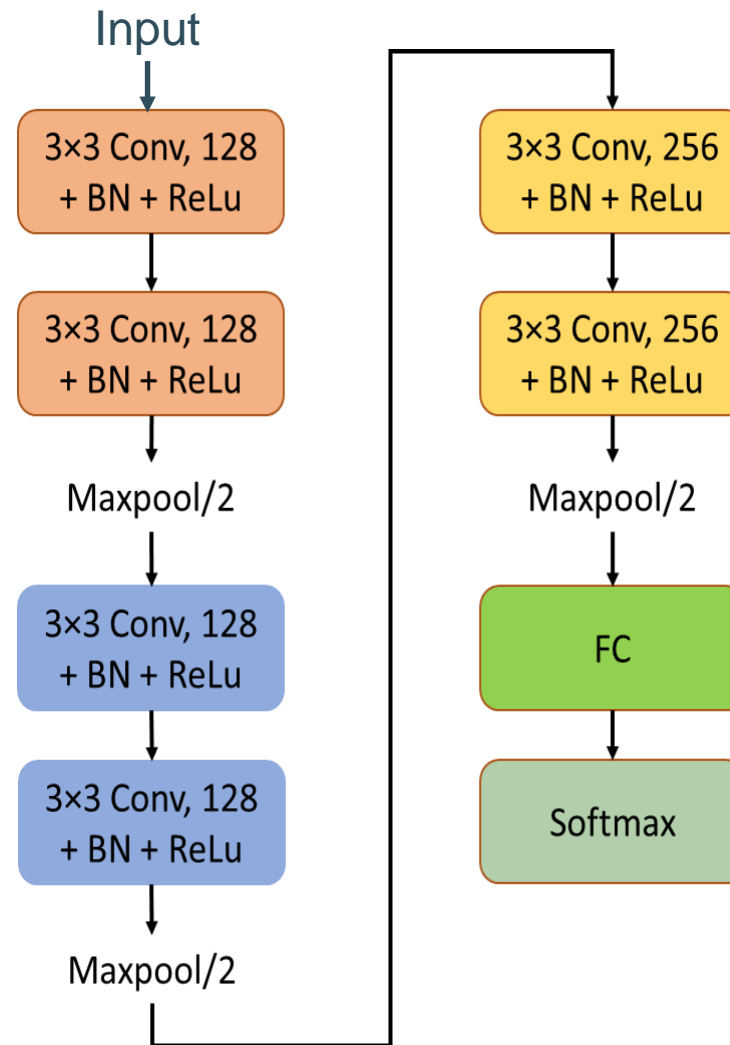


Weights - 4D tensor ( $I \times J \times M \times N$ )  
 $I, J$  filter size.  
 $M$ - input dimension,  $N$ - output dimension.



# Tumor classification: CNN

- CNN Architecture



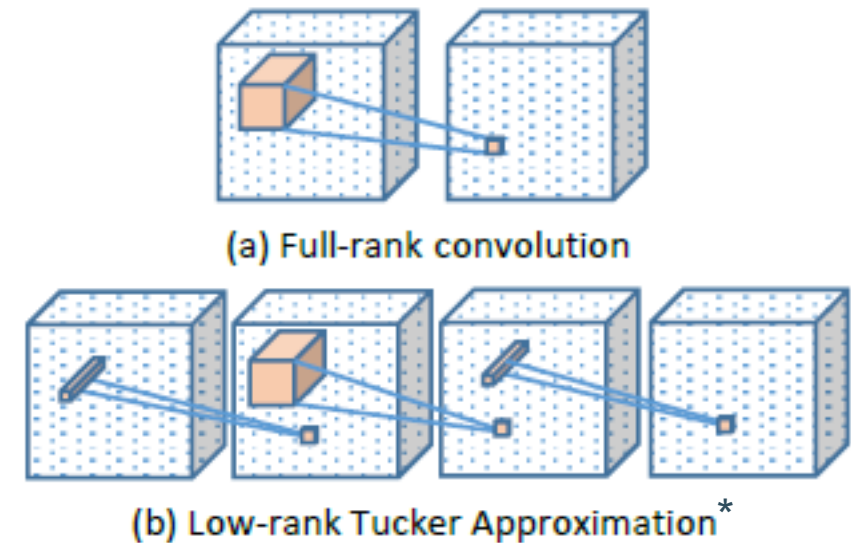
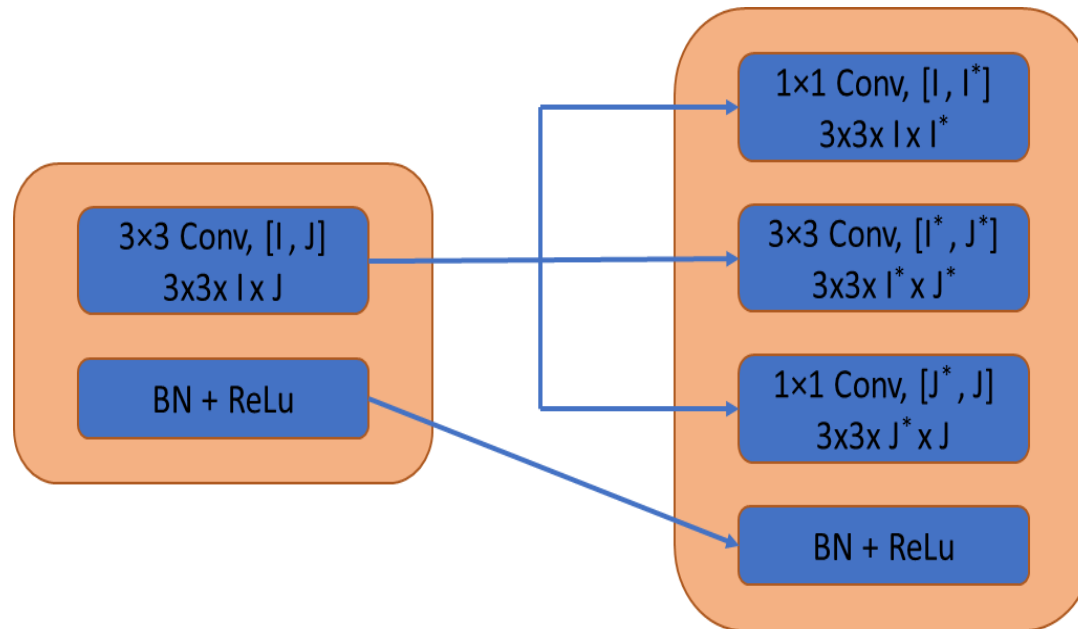
# Tumor classification: CNN

- Apply MLSVD to convolution tensor  $\mathcal{T} \in 3 \times 3 \times I \times J$ .

$$\mathcal{T} = S \times_1 A_1 \times_2 A_2 \times_3 A_3 \times_4 A_4$$

$$\mathcal{T} \approx S I \times_3 \hat{A}_3 \times_4 \hat{A}_4, \quad S I \approx \hat{S} \times_1 A_1 \times_2 A_2$$

$$\hat{S} = S(1:I, 1:J, 1:K^*, 1:L^*), \quad \hat{A}_3 = A_3(:, 1:K^*), \hat{A}_4 = A_4(:, 1:L^*), \quad K^* < K, L^* < L$$



# Tumor classification: CNN

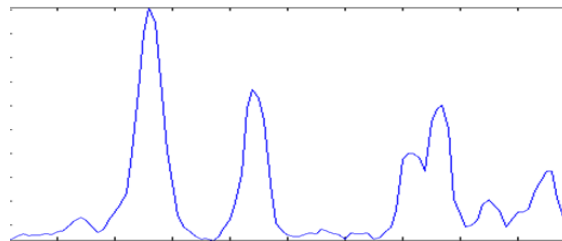
- First train the CNN for 10 epochs.
- Apply low-rank regularization to all the convolution layers except the first one.
- Reduce the dimension in the input and output mode such that the truncated tensor retains 80% of the variance in the respective mode.
- Replace convolution layers with low rank model and initialize the weights with truncated tensor and factor matrix.
- Train the low rank-rank CNN model for 40 more epochs.
- CNN design and training is performed in MatConvNet

# Tumor classification: CNN

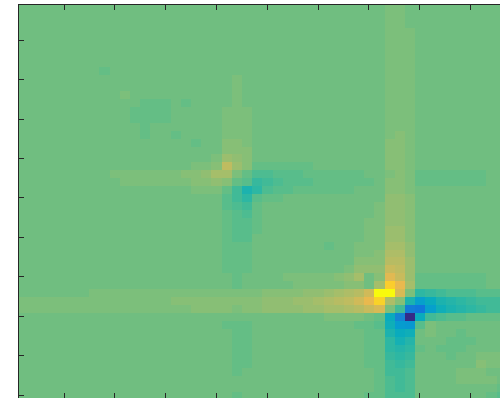
- Given a signal  $S$  evaluated at points  $N = \{n_1, n_2, \dots, n_N\}$ , Loewner matrix is defined as

$$L = \begin{bmatrix} \frac{S(x_1) - S(y_1)}{x_1 - y_1} & \dots & \frac{S(x_1) - S(y_J)}{x_1 - y_J} \\ \vdots & \ddots & \vdots \\ \frac{S(x_I) - S(y_1)}{x_I - y_1} & \dots & \frac{S(x_I) - S(y_J)}{x_I - y_J} \end{bmatrix}$$

With  $X = \{n_1, n_3, \dots\}$  and  $Y = \{n_2, n_4, \dots\}$

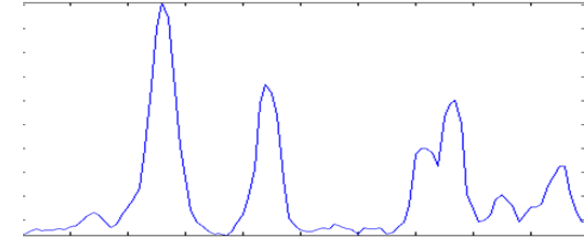


loewnerize →



# Tumor classification: Random forest

- The reduced spectra are used as features.
- Construct 200 tree random forest classifier with three classes: *tumor*, *normal* and *bad*.
- Class imbalance:
  - Tumor class is given more weight compared to others.
- Leave-one-out cross-validation
  - 17 patients (28 MRSI dataset).
  - 5904 voxels in total.



# Results

Tumor	sensitivity	specificity	precision	F1 score
NCPD	81.01%	87.96%	70.36%	0.7437
Random forest	76.89%	<b>94.46%</b>	80.76%	0.7739
CNN	81.58%	94.22%	<b>82.70%</b>	<b>0.8089</b>
CNN + tensor regularization	<b>82.90%</b>	93.18%	81.06%	<b>0.8087</b>

Normal	sensitivity	Specificity	precision	F1 score
NCPD	71.69%	86.06%	63.02%	0.5851
Random forest	84.15%	<b>94.27%</b>	<b>84.08%</b>	0.7702
CNN	<b>87.39%</b>	92.96%	77.76%	<b>0.7862</b>
CNN + tensor regularization	85.85%	93.91%	78.86%	<b>0.7835</b>

# Contents Overview



## 1. Introduction

- Magnetic Resonance Spectroscopic imaging



## 2. Residual Water Suppression

- Hankel-tensor based water suppression
- Löwner-tensor based water suppression



## 3. Tumor tissue type differentiation

- From MRSI
- From MP-MRI

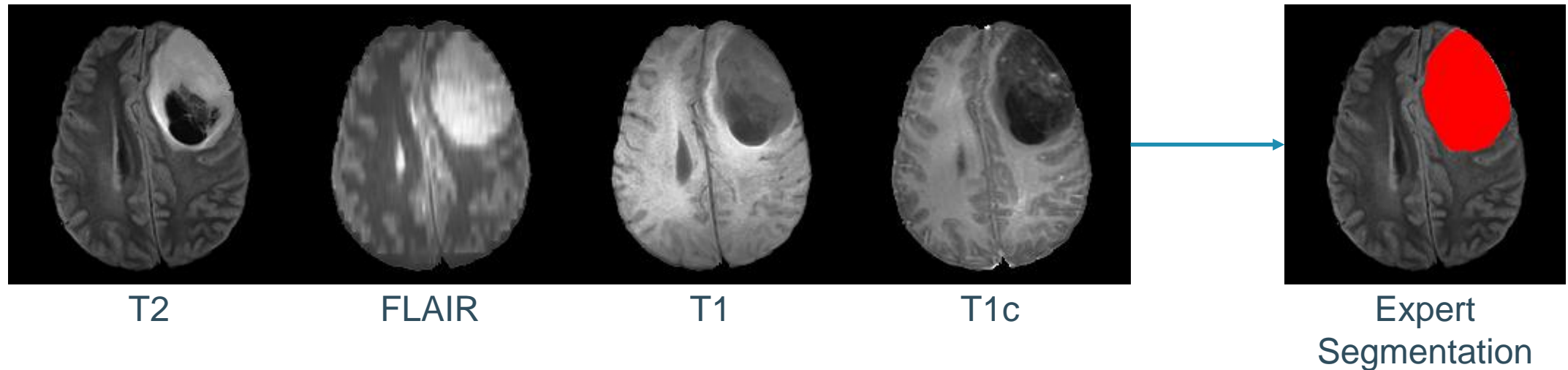


## 4. MRSI tumor voxel classification



## 5. Tumor segmentation from MP-MRI

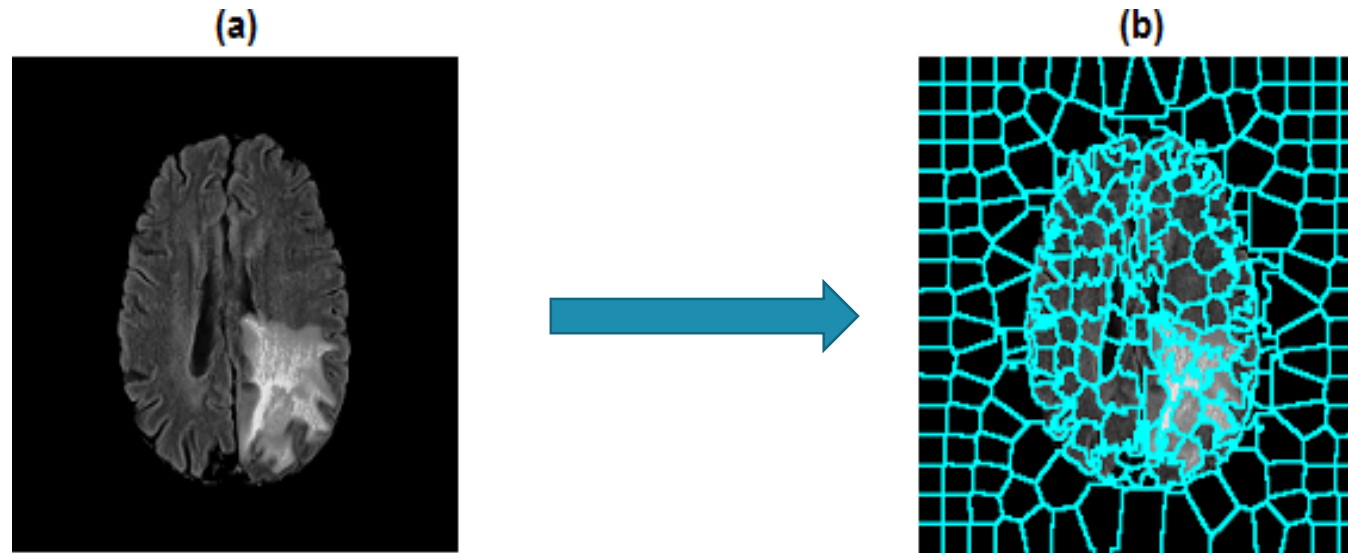
# Multi-Parametric (MP) MRI: Tumor segmentation



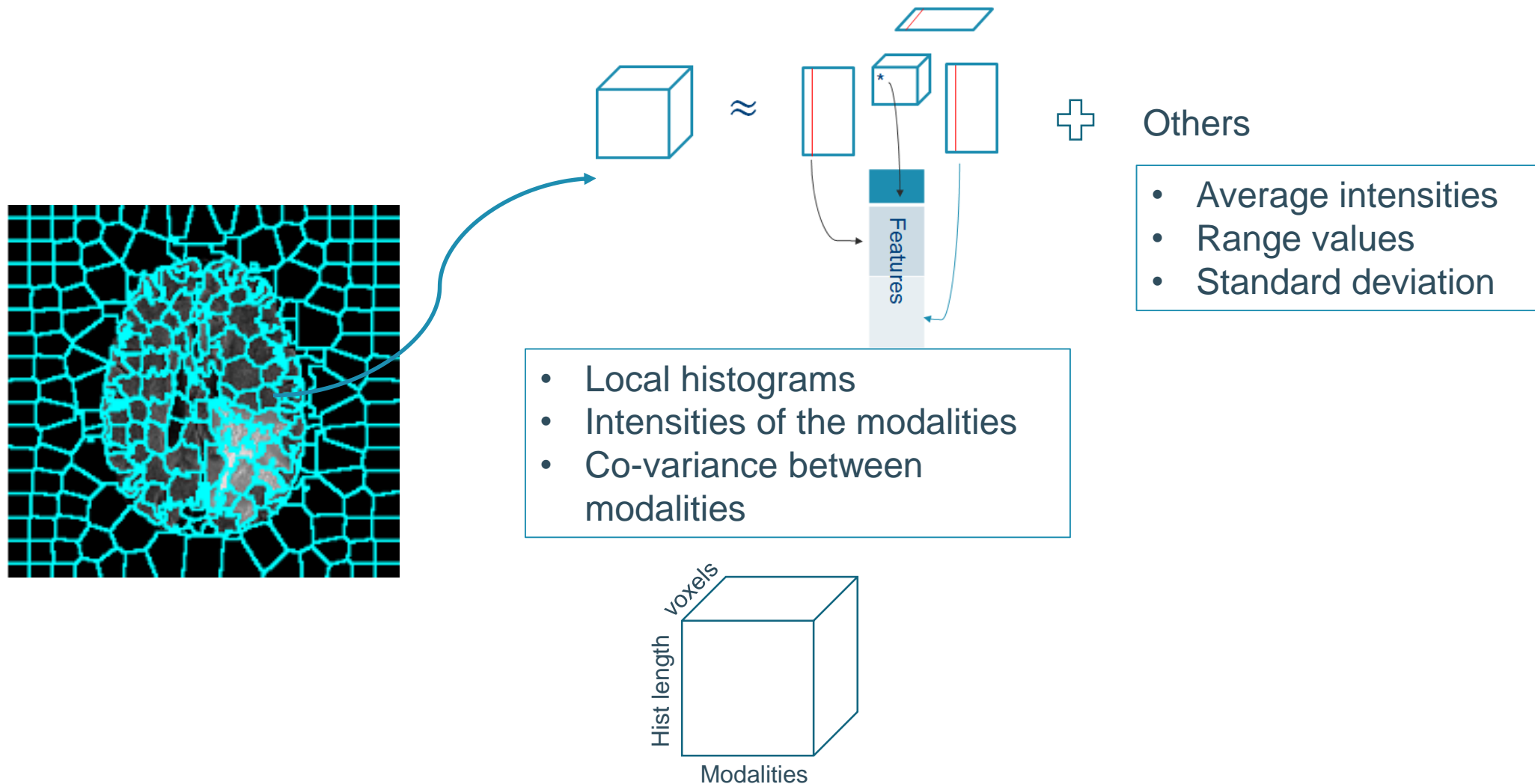


# Super-pixel

- Each image is divided into smaller patches which are better aligned with intensity edges, called superpixels.
- The tissue assignment is done on superpixel-level instead of individual pixel, which helps to reduce computational cost and improve spatial smoothness.

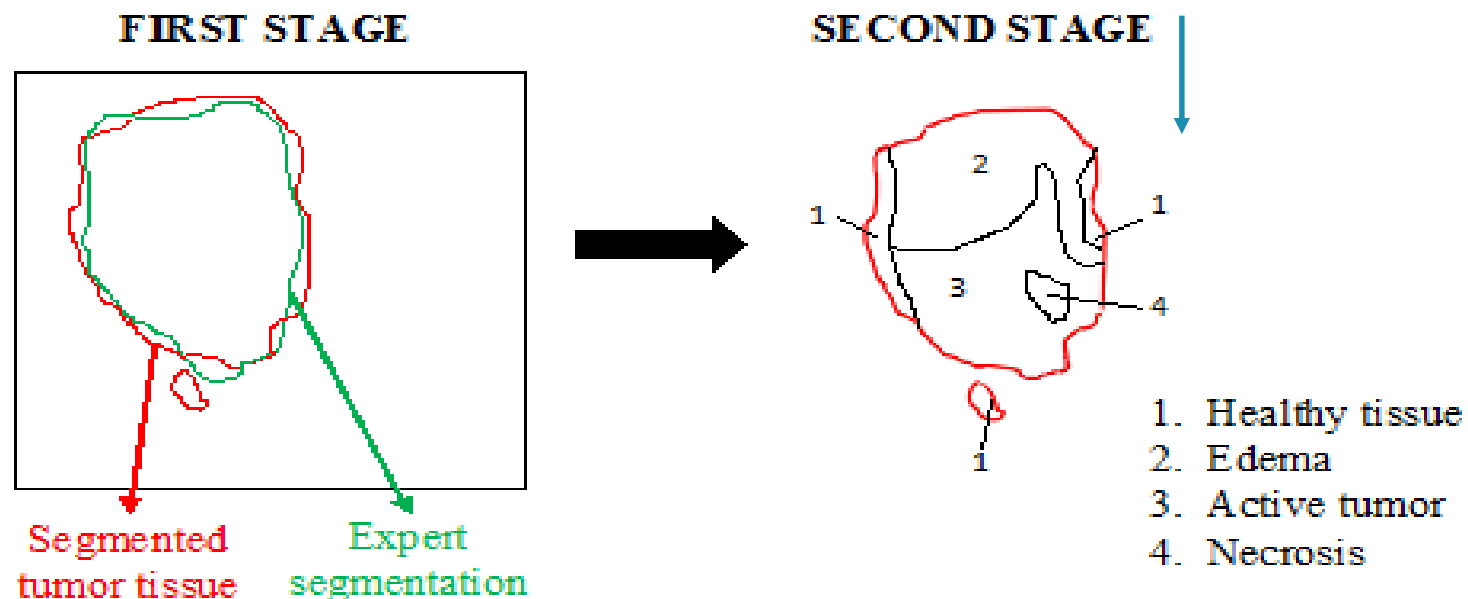


# MP-MRI: RF based tumor segmentation



# MP-MRI: RF based tumor segmentation

- Two-stage Random forest classifier
  - First stage: whole tumor segmentation
  - Second stage: sub-region segmentation from the whole tumor
- Random forest classifier
  - 100 trees for first stage, 200 trees for second stage

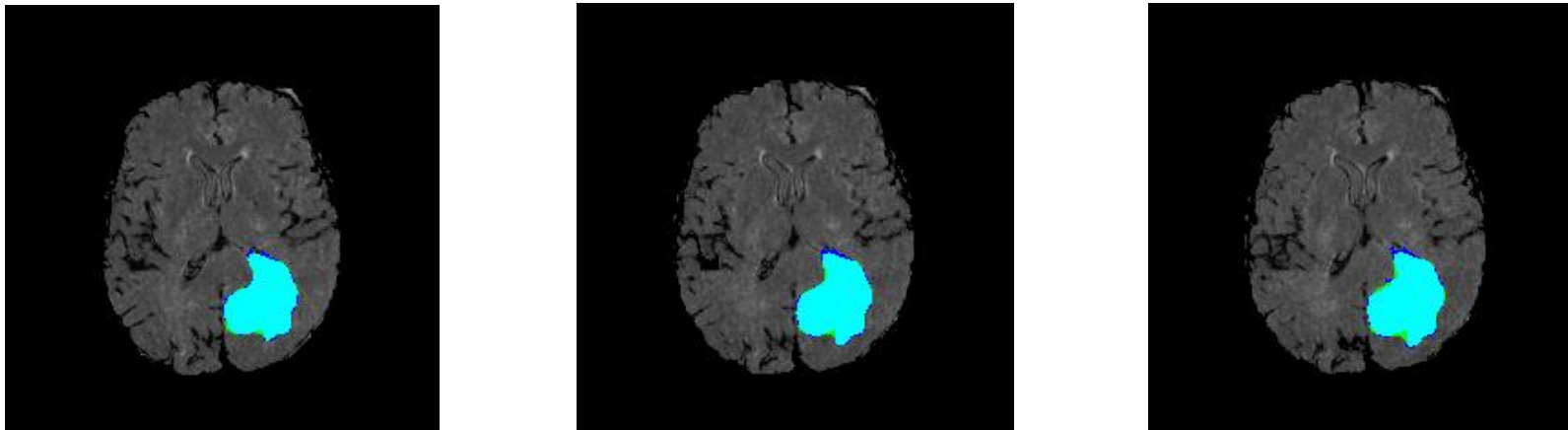


# Tumor Segmentation from MP-MRI: Processing

- Pre-processing:
  - Histogram matching algorithm was applied to all the individual MRI data. Histogram from one of the patients was chosen as reference template histogram.
  - Each image data was scaled between 0-1.
  - Background is removed using Otsu's method.
  - Only the slices where tumor was present was considered for training.
- Post-processing:
  - Image-open followed by image-close operation is performed on the segmented image.

# Tumor Segmentation from MP-MRI: Results

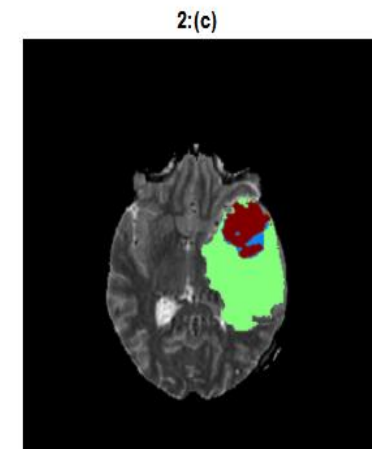
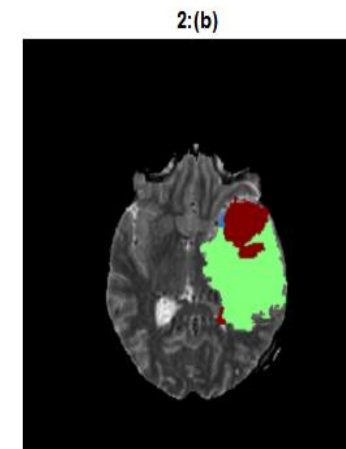
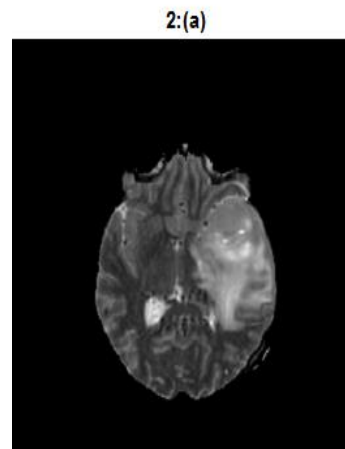
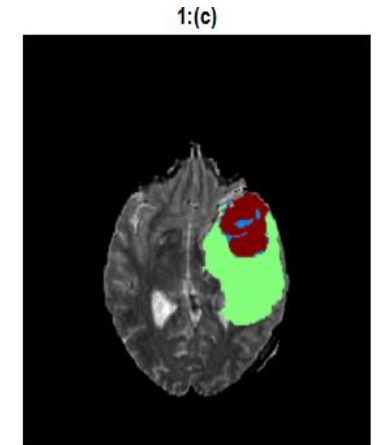
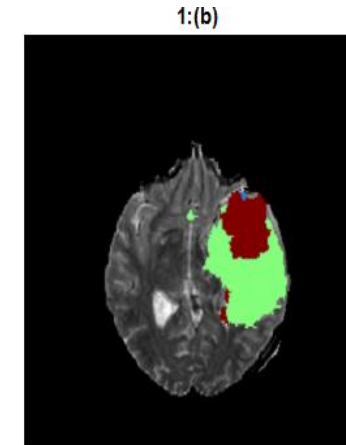
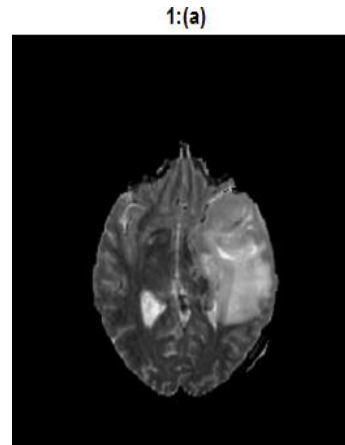
- Tested on BRATS 2017\* validation dataset.
  - Tested on 46 patients
  - Average dice-score of 83.3% with standard deviation of 11.86% for total tumor.



Blue:-Expert; Green:-MLSVD segmentation;  
Cyan:- Overlap between expert and MLSVD

# Results: High Grade Glioma

- 210 High Grade Glioma patients from BRATS 2017 dataset.
- Training – 70% (147)
- Testing – 30% (63)
- Dice score
  - Enhanced tumor (Brown) - 76.1%
  - Tumor core (Brown + blue) - 78.3%
  - Whole Tumor (Brown + blue + green) - 83.3%



# Results:

- BRATS 2017 Validation dataset: 46 patients

Tumor	Dice ET	Dice WT	Dice TC
Mean	61.25%	79.28%	67.34%
Std	30.13%	12.17%	22.15%
Median	74.19%	84.10%	72.91%

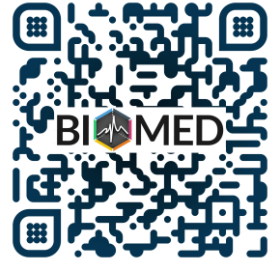
- BRATS 2017 test dataset: 146 patients

Tumor	Dice ET	Dice WT	Dice TC
Mean	50.32%	77.01%	61.05%
Std	30.54%	18.71%	29.54%
Median	63.76%	84.00%	74.16%

# Conclusion

- Tensor based blind source separation methods has better performance than their matrix based counterpart.
  - Residual water suppression
  - Tissue type differentiation.
- Tensor tools can be used in supervised algorithms
  - Comparable results
  - Needs further exploration.





# Thank you!



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